

## **RV-F Series** Industrial robots

### **Compact and powerful** for flexible automation and high reliability





Highly dynamic 6 axis robots for fastest Pick&Place cycles in their class (0.32 s for 12" cycle)

Increased load capacity and extended operating range thanks to compact body and slim arm design

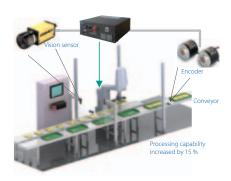
Outstanding IP67 protection for full integration possibilities (Food & Beverage, packaging)

Ethernet, USB, tracking, camera connection, hand I/Os and additional axis connection as standard

# Advanced technology for flexible automation



The F series – designed for flexible automation



Tracking can be used with multiple conveyors at the same time

### Setting new benchmark standards

With the RV-F series of the MELFA robots. Mitsubishi Electric is setting new benchmark standards for speed, flexibility, ease of integration and simplicity of programming. Combining a wide area of coverage with the industry's fastest cycle times, the F series provides a cost-effective means to boost productivity on critical production lines. In addition, with the inclusion of an entry-level model - the RV-2F - Mitsubishi Electric is making it possible for many users to reap the benefits of robotic lifting, positioning and assembling, perhaps for the first time. The robots of the F series are suitable for a wide range of industrial applications and can be deployed in many industries.

### Short cycle times

The robots of the RV-F series achieve the highest speeds in their class thanks to the high-perfomance Mitsubishi Electric servo motors and unique driver control technology developed by Mitsubishi Electric. The resulting reduced cycle time of only 0.32 seconds for a 12" cycle makes for significantly increased productivity and improved continuous operation. This enables high torque output at high rational speed with shortened acceleration/deceleration time.

The extended movement range ensures more flexibility and thus simplifies system planning. Effective access to the entire, almost circular working range has many advantages: it reduces cycle times by avoiding unnecessary movements and increases the tasks which the robot can perform in its working range.

### Performance combined with accuracy

The RV-F series offers many features as standard, which are usually available as optional extras. Every model has connections for pneumatic grippers, Ethernet, USB, tracking functions, camera interface, hand I/O, additional axis controller and an interface for up to 8 additional axes.

Internal routing of cables and air hoses is enabled through internal channels that lead up to the end of the robot arm. This increases the areas of the work envelope and prevents interferences with cables.

Improved trajectory accuracy and optimal motor control tuning is achieved by an operation mode setting function which matches all customer system requirements. This is effective for standard operations and tooling work requiring high accuracy.

The F series naturally fulfils the requirements of the latest safety standards ISO 10218-1 (2011) for robots. UL versions and Korean safety certification are also available.

#### **MELFA RV-F Series**

### Safety features

Many safety features are added to protect staff, hardware and programs.

The accuracy of the robot trajectory can be maintained even when the machine is shut down using an emergency stop. This enables the risk of collisions with peripheral devices and other components to be reduced or even completely avoided.

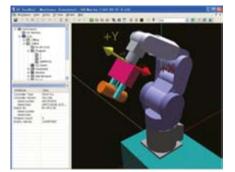
### Intuitive programming and operation

The robots of the RV-F series allow simple automatic operation from the teaching box or direct control via a Mitsubishi GOT. This enables the robot controller status to be uploaded and operations to be controlled directly. Monitoring screens can be set up individually to match the needs of user debugging conditions.

### Versatile connection possibilities

The RV-F series includes a number of user interfaces straight from the factory. These enable image processing systems to be connected directly to the controller and initiated via the standard programming language. Simple parameter structures even enable known systems to be set up in advance with a single mouse click. Two encoder interfaces enable the robot to track two conveyors freely in space and move with them in absolute synchronism. This saves additional costs for positioning units and, above all, time, as the robot is able to fetch, position and machine workpieces while the process is running.

In addition, up to 8 additional axes can be connected directly to the controller. Two of these can be used as additional interpolating axes of the robot. The special feature compared with other systems is that all additionally connected axes can be programmed in exactly the same way as the robot, using the same Teach-Box or the standard RT ToolBox2 software. This avoids the additional expense of software, training and programming.

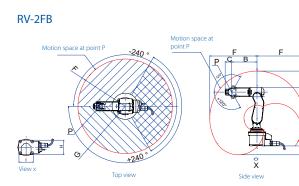


Attachment of a hand created in RT ToolBox2

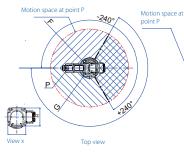


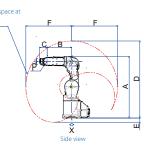
Controlling the robot

### Movement range and dimensions









Dimensions for type	A	В	C	D	E	F	G	Н	I
RV-2FB	623	270	70	799.6	94.6	504.6	139.5	160	160
RV-4FLM	764.9	335	85	998.7	140	648.7	140.4	200	200
RV-7FM	844.4	370	85	1113.4	168.4	713.4	197.4	245	245.7
RV-7FLM	939.4	470	85	1307.7	352.3	907.7	192.8	245.7	245.7

### **MELFA RV-F Series**

### **Specifications**

Robot			RV-2FB	RV-4FLM	RV-7FM	RV-7FLM	
Installation			Floor, wall, ceiling				
Degrees of freedom			6				
Design			Vertical, mutiple-joint type				
Drive system			AC servo motor				
Position detection method			Absolute encoder				
Arm length	N01	mm	230 + 270	245 + 300	340 + 360	430 + 465	
Max. reach radius mm		504	649	713	908		
Maximum speed	J1-axis	deg/s	300	420	360	288	
	J2-axis	deg/s	150	336	401	321	
	J3-axis	deg/s	300	250	450	360	
	J4-axis	deg/s	450	540	337	337	
	J5-axis	deg/s	450	623	450	450	
	J6-axis	deg/s	750	720	720	720	
Maximum composite speed mm/		mm/s	4955	9048	11064	10977	
Cycle time (with 1 kg load) s		0.6	0.36	0.32	0.35		
Payload kg		2	2 4 7				
Position repeatability mm		±0.02					
Operating tem	nperature	°C	0-40				
Weight		kg	19	36	46	48	
Tool wiring		Hand: 4 I/O points Signal cable for the multi-func- tion hand	Hand: 8 inputs/8 outputs (20 pins total) Serial signal cable for parallel I/O (2-pin and 2 pins for power supply) LAN 100BASE-TX (RJ45)				
Tool pneumatic pipes			Ø4x4	Primary: Ø6x2, Secondary: Ø4x8, Ø4x4 (from base portion to forearm)			
Protection class			IP30	IP67 (oil mist), ISO class 3			
Compatible robot controller *				CR750	-F-D/Q		

Robot cont	roller	CR750-Q	CR750-D		
Programming language		MELFA-BASIC V			
Position determination		Teaching, manual data input (MDI)			
	General-purpose I/O	up to 8192	up to 256		
External I/O	Dedicated I/O	Common I/O for multiple CPU	User-defined		
	Gripper status signal inputs	8 inputs			
	External emergency stop	1 (redundant)			
	Door closed contact	1 (redundant)			
	Enabling switch	1 (redundant)			
	Emergency stop additional axes	1 (redundant)			
Interfaces	RS422	1 (Teaching Box)			
	Ethernet	1 (Teaching Box)	1 (Teaching Box) 1 (spare) 10BASE-T/100BASE-TX		
	USB	1 (USB port for PLC CPU)	1 (Mini-B connector, Ver. 2.0)		
	Additional axis	up to 8 (SSCNETIII)			
	Conveyor belt tracking encoder	Q173DPX (optional)	2		
	Expansion slot	—	2		
Power	Input voltage	Single phase 180 V to 253 V AC $^{\odot}$			
supply	Power consumption kVA $^{\odot}$	0.5 – 2.0			
Ambient temperature °C		0-40 (drive unit)/ 0—55 (robot CPU)	0-40		
Dimensions (WxHxD) mm		430x425x174			
Weight kg		approx. 16			
Housing/protection class		Floor mounting/IP20			

<sup>①</sup> The supply voltage should not vary by more than 10 %

<sup>(2)</sup> Without switch-on current. The power consumption depends on the robot arm model.

\* Select the control unit suitable for your application.

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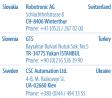
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