

MELSEC System Q

Motion Controller

Installation Manual

SW3RNC-GSVE/GSVHELPE

Art. no.: 147253 01 12 2001 IB(NA)-0300018-F



INTRODUCTION

Thank you for purchasing the Mitsubishi Motion Controller/Personal Machine Controller. This instruction manual describes the handling and precautions of this unit. Incorrect handing will lead to unforeseen events, so we ask that you please read this manual thoroughly and use the unit correctly. Please make sure that this manual is delivered to the final user of the unit and that it is stored for future reference.

Precautions for Safety

Please read this instruction manual and enclosed documents before starting installation, operation, maintenance or inspections to ensure correct usage. Thoroughly understand the machine, safety information and precautions before starting operation.

The safety precautions are ranked as "Warning" and "Caution" in this instruction manual.



When a dangerous situation may occur if handling is mistaken leading to fatal or major injuries.



When a dangerous situation may occur if handling is mistaken leading to medium or minor injuries, or physical damage.

Note that some items described as cautions may lead to major results depending on the situation. In any case, important information that must be observed is described.

For Sate Operations

1. Prevention of electric shocks

¢	Never open the front case or terminal covers while the power is ON or the unit is running, as this may lead to electric shocks.				
Þ	Never run the unit with the front case or terminal cover removed. The high voltage terminal and charged sections will be exposed and may lead to electric shocks.				
< \	Never open the front case or terminal cover at times other than wiring work or periodic inspections even if the power is OFF. The insides of the control unit and servo amplifier are charged and may lead to electric shocks.				
<\$	When performing wiring work or inspections, turn the power OFF, wait at least ten minutes, and then check the voltage with a tester, etc. Failing to do so may lead to electric shocks.				
<\$>	Always ground the control unit, servo amplifier and servomotor with Class 3 grounding. Do not ground commonly with other devices.				
< h >	The wiring work and inspections must be done by a qualified technician.				
<\$>	Wire the units after installing the control unit, servo amplifier and servomotor. Failing to do so may lead to electric shocks or damage.				
<\$>	Never operate the switches with wet hands, as this may lead to electric shocks.				
<\$>	Do not damage, apply excessive stress, place heavy things on or sandwich the cables, as this may lead to electric shocks.				
<\$>	Do not touch the control unit, servo amplifier or servomotor terminal blocks while the power is ON, as this may lead to electric shocks.				
< h>	Do not touch the internal power supply, internal grounding or signal wires of the control unit and servo amplifier, as this may lead to electric shocks.				

2. For fire prevention

- Install the control unit, servo amplifier, servomotor and regenerative resistor on inflammable material. Direct installation on flammable material or near flammable material may lead to fires.
- ▲ If a fault occurs in the control unit or servo amplifier, shut the power OFF at the servo amplifier's power source. If a large current continues to flow, fires may occur.
- When using a regenerative resistor, shut the power OFF with an error signal. The regenerative resistor may abnormally overheat due to a fault in the regenerative transistor, etc., and may lead to fires.
- Always take heat measures such as flame proofing for the inside of the control panel where the servo amplifier or regenerative resistor is installed and for the wires used. Failing to do so may lead to fires.

3. For injury prevention

- Do not apply a voltage other than that specified in the instruction manual on any terminal. Doing so may lead to destruction or damage.
- Do not mistake the terminal connections, as this may lead to destruction or damage.
- \land Do not mistake the polarity (+/–), as this may lead to destruction or damage.
- The servo amplifier's heat radiating fins, regenerative resistor and servo amplifier, etc., will be hot while the power is ON and for a short time after the power is turned OFF. Do not touch these parts as doing so may lead to burns.
- Always turn the power OFF before touching the servomotor shaft or coupled machines, as these parts may lead to injuries.
- ⚠️ Do not go near the machine during test operations or during operations such as teaching. Doing so may lead to injuries.

4. Various precautions

Strictly observe the following precautions. Mistaken handling of the unit may lead to faults, injuries or electric shocks.

(1) System structure

	Always install a leakage breaker on the control unit and servo amplifier power source. If installation of a magnetic contactor for power shut off during an error, etc., is specified in				
	the instruction manual for the servo amplifier, etc., always install the magnetic contactor.				
	Install an external emergency stop circuit so that the operation can be stopped immediately and the power shut off.				
Â	Use the control unit, servo amplifier, servomotor and regenerative resistor with the combinations listed in the instruction manual. Other combinations may lead to fires or faults.				
Â	If safety standards (ex., robot safety rules, etc.,) apply to the system using the control unit, servo amplifier and servomotor, make sure that the safety standards are satisfied.				
Â	If the operation during a control unit or servo amplifier error and the safety direction operation of the control unit differ, construct a countermeasure circuit externally of the control unit and servo amplifier.				
Â	In systems where coasting of the servomotor will be a problem during emergency stop, servo OFF or when the power is shut OFF, use dynamic brakes.				
Â	Make sure that the system considers the coasting amount even when using dynamic brakes.				
Â	In systems where perpendicular shaft dropping may be a problem during emergency stop, servo OFF or when the power is shut OFF, use both dynamic brakes and magnetic brakes.				
Â	The dynamic brakes must be used only during emergency stop and errors where servo OFF occurs. These brakes must not be used for normal braking.				
Â	The brakes (magnetic brakes) assembled into the servomotor are for holding applications, and must not be used for normal braking.				
Â	Construct the system so that there is a mechanical allowance allowing stopping even if the stroke end limit switch is passed through at the max. speed.				
À	Use wires and cables that have a wire diameter, heat resistance and bending resistance compatible with the system.				

- \triangle Use wires and cables within the length of the range described in the instruction manual.
- The ratings and characteristics of the system parts (other than control unit, servo amplifier, servomotor) must be compatible with the control unit, servo amplifier and servomotor.
- 1 Install a cover on the shaft so that the rotary parts of the servomotor are not touched during operation.
- There may be some cases where holding by the magnetic brakes is not possible due to the life or mechanical structure (when the ball screw and servomotor are connected with a timing belt, etc.). Install a stopping device to ensure safety on the machine side.

(2) Parameter settings and programming

- ∴ Set the parameter values to those that are compatible with the control unit, servo amplifier, servomotor and regenerative resistor model and the system application. The protective functions may not function if the settings are incorrect.
- The regenerative resistor model and capacity parameters must be set to values that conform to the operation mode, servo amplifier and servo power unit. The protective functions may not function if the settings are incorrect.
- ∴ Set the mechanical brake output and dynamic brake output validity parameters to values that are compatible with the system application. The protective functions may not function if the settings are incorrect.
- A Set the stroke limit input validity parameter to a value that is compatible with the system application. The protective functions may not function if the setting is incorrect.
- ∴ Set the servomotor encoder type (increment, absolute position type, etc.) parameter to a value that is compatible with the system application. The protective functions may not function if the setting is incorrect.
- ∴ Set the servomotor capacity and type (standard, low-inertia, flat, etc.) parameter to values that are compatible with the system application. The protective functions may not function if the settings are incorrect.
- A Set the servo amplifier capacity and type parameters to values that are compatible with the system application. The protective functions may not function if the settings are incorrect.
- ∴ Use the program commands for the program with the conditions specified in the instruction manual.
- ∴ Set the sequence function program capacity setting, device capacity, latch validity range, I/O assignment setting, and validity of continuous operation during error detection to values that are compatible with the system application. The protective functions may not function if the settings are incorrect.
- Some devices used in the program have fixed applications, so use these with the conditions specified in the instruction manual.
- The input devices and data registers assigned to the link will hold the data previous to when communication is terminated by an error, etc. Thus, an error correspondence interlock program specified in the instruction manual must be used.
- ∴ Use the interlock program specified in the special function unit's instruction manual for the program corresponding to the special function unit.

(3) Transportation and installation

Vibration

Transport the product with the correct method according to the weight. 1 Use the servomotor suspension bolts only for the transportation of the servomotor. Do not transport the servomotor with machine installed on it. Do not stack products past the limit. Mhen transporting the control unit or servo amplifier, never hold the connected wires or cables. When transporting the servomotor, never hold the cables, shaft or detector. When transporting the control unit or servo amplifier, never hold the front case as it may fall off. When transporting, installing or removing the control unit or servo amplifier, never hold the edges. 1. Install the unit according to the instruction manual in a place where the weight can be withstood. 1. Do not get on or place heavy objects on the product. Always observe the installation direction. Keep the designated clearance between the control unit or servo amplifier and control panel inner surface or the control unit and servo amplifier, control unit or servo amplifier and other devices. 1 Do not install or operate control units, servo amplifiers or servomotors that are damaged or that have missing parts. Do not block the intake/outtake ports of the servomotor with cooling fan. 1 Do not allow conductive matter such as screw or cutting chips or combustible matter such as oil enter the control unit, servo amplifier or servomotor. The control unit, servo amplifier and servomotor are precision machines, so do not drop or apply strong impacts on them. Securely fix the control unit and servo amplifier to the machine according to the instruction manual. If the fixing is insufficient, these may come off during operation. Always install the servomotor with reduction gears in the designated direction. Failing to do so may lead to oil leaks. Store and use the unit in the following environmental conditions. Condition Environment Control unit/servo amplifier Servomotor 0°C to +55°C Ambient 0°C to +40°C temperature (With no freezing) (With no freezing) According to each instruction 80%RH or less Ambient humidity manual. (With no dew condensation) According to each instruction Storage -20°C to +65°C manual. temperature Indoors (where not subject to direct sunlight). Atmosphere No corrosive gases, flammable gases, oil mist or dust must exist. Altitude 1000m (305 Feet) or less above sea level.

According to each instruction manual.

- Mhen coupling with the synchronization encoder or servomotor shaft end, do not apply impact such as by hitting with a hammer. Doing so may lead to detector damage.
- ∴ Do not apply a load larger than the tolerable load onto the servomotor shaft. Doing so may lead to shaft breakage.
- Mhen not using the unit for a long time, disconnect the power line from the control unit or servo amplifier.
- A Place the control unit and servo amplifier in static electricity preventing vinyl bags and store.

(4) Wiring

Correctly and securely wire the wires. Reconfirm the connections for mistakes and the terminal screws for tightness after wiring. Failing to do so may lead to run away of the servomotor. After wiring, install the protective covers such as the terminal covers to the original positions. 1. Do not install a phase advancing capacitor, surge absorber or radio noise filter (option FR-BIF) on the output side of the servo amplifier. Correctly connect the output side (terminals U, V, W). Incorrect connections will lead the servomotor to operate abnormally. No not connect a commercial power supply to the servomotor, as this may lead to trouble. 1 Do not mistake the direction of the surge absorbing diode Servo amplifier installed on the DC relay for the control signal output of VIN brake signals, etc. Incorrect installation may lead to signals (24VDC) not being output when trouble occurs or the protective functions not functioning. Control output 1 Do not connect or disconnect the connection cables signal between each unit, the encoder cable or sequence expansion cable while the power is ON. Securely tighten the cable connector fixing screws and fixing mechanisms. Insufficient fixing may lead to the cables combing off during operation.

 \triangle Do not bundle the power line or cables.

(5) Trial operation and adjustment

Â	Confirm and adjust the program and each parameter before operation. Unpredictable movements may occur depending on the machine.				
Â	Extreme adjustments and changes may lead to unstable operation, so never make them.				
Â	When using the absolute position system function, on starting up, and when the controller or absolute value motor has been replaced, always perform a home position return.				

(6) Usage methods

- Immediately turn OFF the power if smoke, abnormal sounds or odors are emitted from the control unit, servo amplifier or servomotor.
- Always execute a test operation before starting actual operations after the program or parameters have been changed or after maintenance and inspection.
- $\underline{\wedge}$ The units must be disassembled and repaired by a qualified technician.
- 1 Do not make any modifications to the unit.
- ∴ Keep the effect or magnetic obstacles to a minimum by installing a noise filter or by using wire shields, etc. Magnetic obstacles may affect the electronic devices used near the control unit or servo amplifier.
- \triangle Use the units with the following conditions.

ltem	Conditions
Input power	According to the separate instruction manual.
Input frequency	According to the separate instruction manual.
Tolerable momentary power failure	According to the separate instruction manual.

(7) Remedies for errors



(8) Maintenance, inspection and part replacement

- $\underline{\land}$ Perform the daily and periodic inspections according to the instruction manual.
- Perform maintenance and inspection after backing up the program and parameters for the control unit and servo amplifier.
- \triangle Do not place fingers or hands in the clearance when opening or closing any opening.
- Periodically replace consumable parts such as batteries according to the instruction manual.

⚠️ Do not touch the lead sections such as ICs or the connector contacts.					
Do not place the control unit or servo amplifier on metal that may cause a power leakage or wood, plastic or vinyl that may cause static electricity buildup.					
m m m m m m m m m m m m m					
\triangle When replacing the control unit or servo amplifier, always set the new unit settings correctly.					
When the controller or absolute value motor has been replaced, carry out a home position return operation using one of the following methods, otherwise position displacement could accur.					
Occur.					
power again, then perform a home position return operation.					
 Using the backup function of the peripheral device software, load the data backed up before replacement. 					
After maintenance and inspections are completed, confirm that the position detection of the absolute position detector function is correct.					
1 Do not short circuit, charge, overheat, incinerate or disassemble the batteries.					
The electrolytic capacitor will generate gas during a fault, so do not place your face near the control unit or servo amplifier.					
The electrolytic capacitor and fan will deteriorate. Periodically change these to prevent secondary damage from faults. Replacements can be made by the Service Center or Service Station.					

(9) Disposal

- $\underline{\land}$ Dispose of this unit as general industrial waste.
- \triangle Do not disassemble the control unit, servo amplifier or servomotor parts.
- $\underline{\Uparrow}$ Dispose of the battery according to local laws and regulations.

(10) General cautions

All drawings provided in the instruction manual show the state with the covers and safety partitions removed to explain detailed sections. When operating the product, always return the covers and partitions to the designated positions, and operate according to the instruction manual.

Revisions

*The manual number is given on the bottom left of the back cover.

Print Date	*Manual Number	Revision			
Jul., 2000	IB(NA)-0300018-A	First edition			
Jan., 2001	IB(NA)-0300018-B	Addition			
		Addition of SW3RN-GSV43P description			
Mar., 2001	IB(NA)-0300018-C	Addition			
		Addition of RS232C communication description, Section 4.5			
Apr., 2001	IB(NA)-0300018-D	Addition			
		Addition of SW3RN-GSV51P description, Section 3.6, Section 4.6,			
		Section 4.6.1			
		Correction			
		CONTENTS, Section 2.2 (1), Section 2.2 (2), Section 2.3, Section 2.5,			
		Section 3.1,			
Aug., 2001	IB(NA)-0300018-E	Addition			
		Addition of SW20RN-DOCPRNP and SW20RN-LADDERP description,			
		Section 3.4.2, Section 3.4.3, Section 3.4.4, Section 3.4.5, Section 3.4.6,			
		Chapter5			
		Correction			
		CONTENTS, Section 2.2 (1), Section 2.2 (2), Section 2.3, Section 3.1,			
		Section 3.2, Section 4.1, Section 4.1.1, Section 4.1.2, Section 4.2,			
Dec., 2001	IB(NA)-0300018-F	Addition			
		Addition of Windows 2000 and A10BD-PCF interface board description,			
		Section 4.1.3, Section 4.3.1, Section 4.3.2, Section 3.7, Section 5.5			
		Correction			
		Section 2.2, Section 2.5, Section 3.1, Section 3.3, Section 3.4.1, Section 3.4.2,			
		Section 3.4.3, Section 3.4.4, Section 3.4.5, Section 3.4.6, Section 4.6.1, Section 5.1, Section 5.2, Section 5.2, Section 5.4			
		Section 5.1, Section 5.2, Section 5.3, Section 5.4			

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1. OVERVIEW

This manual explains the installation procedures, operating environment and system configuration of the SW3RNC-GSVE motion controller startup support software packages and SW3RNC-GSVHELPE operating manuals.

1.1 Features

The SW3RNC-GSVE motion controller startup support software packages offer a group of software packages which totally supports the control program design environment, maintenance engineering environment and application design environment for configuring a system using the motion controllers. The software can be used for various applications such as motion controller startup, centralized monitoring and data collection. In addition, the software supports the development of user-original application software to structure a flexible machine.

2. SYSTEM CONFIGURATION

2.1 Software Makeup

Each software package is made up of the following software.

(1) SW3RNC-GSVE: Motion controller startup support software packages The packages and versions of SW3RNC-GSVE Ver. H are as indicated in Table 2.1.

	Туре	Product Name	Description	Version
	SW3RN-GSV13P *1	Transfer/assembly software	Supports programming, monitor and test for controller OS SV13.	00E
	SW3RN-GSV22P *2	Automatic machine software	Supports programming, monitor and test for controller OS SV22.	00E
	SW3RN-GSV43P *3	Machine tool peripheral software	Supports programming, monitor and test for controller OS SV43.	00D
	SW3RN-GSV51P *4	Special-purpose robot software	Supports programming, monitor and test for controller OS SV51.	00B
	SW3RN-CAMP *5	Cam data creation software	Creates the cam patterns for cam control of controller OS SV22. Needed for use of cams.	00E
Control program design environment	SW3RN-LADDERP *6 (For Office 97)	Loddor oditing ooffware	Supports ladder programming of the motion	00F
	SW20RN-LADDERP *6 (For Office 2000)	Ladder editing software	CPU.	00B
	SW3RN-DOCPRNP *7 (For Office 97)		Converts the program and parameter data set on GSV13P, GSV22P,GSV43P, GSV51P or CAMP into the Word/Excel file format, and	00H
	SW20RN-DOCPRNP *7 (For Office 2000)	software	supports printing them. Converts the sampling data saved on DOSCP into the Excel file format, dumps and graphs them, and supports printing them.	00D
Maintenance engineering environment	SW3RN-DOSCP *8	Digital oscilloscope software	Offers the maintenance engineering environment. Shows the motion system control status in terms of waveform and effective for survey, troubleshooting and analysis.	00E
User application design environment	SW3RN-SNETP *9	SSCNET communication system software	Links the motion controller and personal computer by SSCNET or RS232C communication to access data. When SSCNET communication is used, supports the communication API designed for user application software (VB, VC++).	00J

Table 2.1 Packages of SW3RNC-GSVE Ver. H

*1 Hereafter abbreviated to GSV13P.

- *2 Hereafter abbreviated to GSV22P.
- *3 Hereafter abbreviated to GSV43P.
- *4 Hereafter abbreviated to GSV51P.
- *5 Hereafter abbreviated to CAMP.
- *6 Hereafter abbreviated to LADDERP.
- *7 Hereafter abbreviated to DOCPRNP.
- *8 Hereafter abbreviated to DOSCP.
- *9 Hereafter abbreviated to SNETP.
 - *: Among the above software packages marked *1 to *5, install the necessary one according to the controller OS used.

Install either of the software packages marked *6, *7 depending on the operating environment. You cannot install and operate SW3RN-[][]P and SW20RN-[][]P together.

(2)	SW3RNC-GSVHELPE: Motion controlle	r startup	support software of	operating
	manuals			

No.	Manual	Description
1	SW3RN-GSV13P operating manual	
2	SW3RN-GSV22P operating manual	
3	SW3RN-GSV43P operating manual	
4	SW3RN-GSV51P operating manual	
5	SW3RN-CAMP operating manual	Evolution the corresponding energians
6	SW3RN-LADDERP operating manual	Explains the corresponding operations.
7	SW20RN-LADDERP operating manual	
8	SW3RN-DOCPRNP operating manual	
9	SW20RN-DOCPRNP operating manual	
10	SW3RN-DOSCP operating manual	
11	SW3RN-SNETP operating manual	Explains the corresponding operations. Explains the communication API functions.

*Any of the above operating manuals can be browsed from the "Help" menu of the corresponding software package after installation.

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IMPORTANT

- (1) When installing SW3RNC-GSVE (Ver. 00H) newly, refer to "3.1 Installation" and perform installation.
- (2) When updating SW3RNC-GSVE to Ver. 00H, refer to "3.7 Updating Instructions and Procedures" and perform updating.

2.2 System Configuration



(1) When using a desktop personal computer

P	OINT										
(1)	The interface board and interface card cannot be used together.										
(2)	On some	some personal computers, the digital oscilloscope may not perform									
	sampling.										
	In that case, check the BIOS's ISA device memory and IRQ settings. (Fo										
(2)	the BIOS	Settings, refer to	o the manual o	t your persona	al computer.)						
(3)	interface	board and boot t	the personal of	omputer witho	i teniove the	oina					
	reinstalle	d Windows NT/9	98 may not sta	irt or may not	run properly	Cing					
	When re	moving the interfa	ace board fron	n the personal	computer, you	J					
	need to	stop the SSCNET	communicati	on driver.							
	For the v	vay to stop, refer	to "4.5 Stoppin	ng the SSCNE	T Communica	tion					
	Driver".					Driver".					
(4)) You cannot fit and use the A30BD-PCF and A10BD-PCF interface										
	boards together.										
(5)	boards to	ogether.	be used in the								
(5)	boards to	ogether. face boards can	be used in the	following env	ironment.						
(5)	boards to	ogether. face boards can	be used in the Windows 98	following env	CF Interface ironment. Windows 2000						
(5)	A30BD-	ogether. face boards can PCF interface board	be used in the Windows 98	Following env	ironment. Windows 2000						
(5)	A30BD-I	PCF interface board built-in type)	be used in the Windows 98	Following env	Windows 2000						
(5)	A30BD- (ISA bus A10BD-	PCF interface board built-in type) PCF interface board built in type)	be used in the Windows 98	Windows NT	Windows 2000						
(5)	A30BD-I (ISA bus A10BD-I (PCI bus	PCF interface board built-in type) PCF interface board built-in type)	be used in the Windows 98	Windows NT	Windows 2000						
(5)	A30BD- (ISA bus (PCI bus	PCF interface board built-in type) PCF interface board built-in type)	be used in the Windows 98	Windows NT	VF Interface ironment. Windows 2000 × O Usable: O Unusable: ×						
(5)	A30BD-I (ISA bus A10BD-I (PCI bus	PCF interface board built-in type) PCF interface board built-in type) PCF interface board built-in type)	be used in the Windows 98 O A10BD-PCF ir	following env Windows NT O	VF Interface ironment. Windows 2000 × O Usable: O Unusable: × Is in Windows I	NT,					



(2) When using a notebook computer

P	OINT						
(1)	The inte	rface board and in	nterface card o	annot be used	d together.		
(2)	On some	n some personal computers, the digital oscilloscope may not perform					
	sampling.						
	In that ca	ase, use the card	enabler suppl	ied by the pers	sonal computer		
	maker of	r check the PC ca	ard controller s	ettings (BIOS	settings). (For the		
$\langle \alpha \rangle$	BIOS se	ttings, refer to the	e manual of yo	ur personal co	mputer.)		
(3)		20WS 98/2000, Ins	Sent the Interna	ting up the Se	e personal		
	commun		SINE I F allu se	ung up the So			
	(SNFTP	can be reinstalle	d with the inte	face card load	ded)		
(4)	If. after S	SSCNET commun	nication has be	en made. vou	remove the		
()	interface	card and boot th	e personal co	nputer without	t that card being		
	reinstalle	ed, Windows NT r	nay not start c	or may not run	properly.		
	For Wind	dows NT, you nee	ed to stop the	SSCNET com	munication driver		
	when rea	moving the interfa	ace card.				
	For the v	vay to stop, refer	to "4.5 Stoppi	ng the SSCNE	T Communication		
	Driver".						
	(For Windows 98/2000, use the plug and play function to remove. Using				to remove. Using		
(5)	The inter	tion will not cause	e sucn pnenon	nena.) allowing onvir	onmont		
(5)	5) I ne interface cards can be used in the following environment.						
			Windows 98	Windows NT	Windows 2000		
	A30CD-	PCF interface card	0	0	0		
					Usable: •		

2.3 Component List

Name	Туре	Remarks			
SSCNET interface board	A30BD-PCF	ISA bus loading type, 2 channels/board			
SSCINET INTERNACE DUARD	A10BD-PCF	PCI bus loading type, 2 channels/board			
SSCNET interface card	A30CD-PCF	PCMCIA type II, 1 channel/card			
	A270BDCBL 3M	For A30BD-PCF, A10BD-PCF 3m			
	A270BDCBL 5M	For A30BD-PCF, A10BD-PCF 5m			
Communication apple	A270BDCBL 10M	For A30BD-PCF, A10BD-PCF 10m			
Communication capie	A270CDCBL 3M	For A30CD-PCF, 3m			
	A270CDCBL 5M	For A30CD-PCF, 5m			
	A270CDCBL 10M	For A30CD-PCF, 10m			
		Diatrend Corp. make recommended			
RS232C/422 converter	DAFXIH-CABV	Diatrend Corp.			
built-in cable		1-1-55, Tsuneyoshi, Konohana-ku,			
		Osaka City 554-0052, Japan			

2.4 SW3RNC-GSVSETE Makeup

Туре	Product Packed	Remarks
	SW3RNC-GSVE	Motion controller startup support software packages on 1 CD-ROM
SW3RNC-GSVSETE	SW3RNC-GSVHELPE	Motion controller startup support software operating manuals on 1 CD-ROM
	Installation manual	IB(NA)-0300018
	A30CD-PCF	PCMCIA type II, 1 channel/card
	A270CDCBL 3M	For A30CD-PCF, 3m

2.5 **Operating Environment**

Item	Description
	133MHz or more Pentium personal computer where Windows
Computer	NT/98 operates or 233MHz or more Pentium II personal computer
	where Windows 2000 operates (PC/AT compatible)
	Windows NT 4.0 (Service Pack 2 or later)
	Windows 98
Operating system	Windows 2000
	 In Windows NT 4.0, the use needs Microsoft Internet Explorer
	3.01 or higher.
Required memory	32MB or more recommended (64MB or more for Windows 2000)
Hard disk free space	Refer to the table below.
Diale drive	3.5 inch (1.44MB) floppy disk drive
Disk drive	CD-ROM disk drive
Display	Resolution 800×600 dots, 256 or more display colors

The operating environment is indicated below.

The following spaces are required according to the software installed.

Turne	Size				
гуре	SW3RNC-GSV	IC-GSVE SW3RNC-GSVHELPE			
SW3RN-GSV13P	26MB		23MB		
SW3RN-GSV22P	27MB		30MB		
SW3RN-GSV43P	17MB		10MB		
SW3RN-GSV51P	27MB		10MB		
SW3RN-CAMP	1MB	1MB			
SW3RN-LADDERP	14MB 8MB		8MB		
SW20RN-LADDERP	20RN-LADDERP 14MB		8MB		
SW3RN-DOSCP	8MB		2MB		
	Standard	2MB			
SW3RN-SNETP	Custom	2110	1MB		
	(when all are selected)	SIVID			
SW3RN-DOCPRNP	25MB		2MB		
SW20RN-DOCPRNP	23MB		3MB		

POINT

- (1) If you have any question as to the operating procedure of Windows in operating this software, refer to the Windows manual or commercially available guidebooks.
- (2) Depending on the system font size of Windows NT/98/2000, the screen may not be displayed properly.

Use a small size font.

This chapter provides how to install and uninstall GSV13P, GSV22P, GSV43P, GSV51P, CAMP, LADDERP, DOSCP, SNETP and/or DOCPRNP.

3.1 Installation

This section gives the way to install and uninstall GSV13P, GSV22P, GSV43P, GSV51P, CAMP, LADDERP, DOSCP, SNETP and/or DOCPRNP.

P	OINT	
(1)	Before s	tarting installation, close all other applications running on
(2)	If you ins 95/98 pe and insta	stall this software from the CD-ROM drive of the other Windows ersonal computer via a network, "Setup.Exe not found." appears allation cannot be made.
	After ma the CD-F the netw	king setting to share the folder of this software to be installed in ROM drive of the Windows 95/98 personal computer, assign it to ork drive, execute "Setup.Exe", and install this software.
(3)	If the ins space ha then pre- and char compres	tallation of this software into the drive compressed in the drive as stopped at any point, increase the free space of the drive and ss the [Retry] button to resume, or press the [Stop] button to stop nge the drive to the one where the installation destination is not used.
(4)	In any of reinstall • Installa • Installa • Softwa	the following cases, always uninstall (refer to Section 3.5) and the software. ation failed midway ation destination drive is to be changed are is to be reinstalled

IMPORTANT

(1)	When using SW3RN-GSV43P, ye	ou must add necess	sary data to the	
	"Config.nt" or "Config.sys" file.			
	For addition of necessary data, re	efer to "3.4.1 Precau	itions for Using	
	SW3RN-GSV43P".			
(2)	Different versions of SNETP and	DOCPRNP cannot	coexist and run.	
. ,	Always reinstall them after uninsta	alling them.		
	(However, when Windows NT, W	indows 98 and Win	dows 2000 are	
	installed in a single personal com	puter, the same ver	sions of SNETP and	d
	DOCPRNP can coexist in respect	tive drives without a	ny problem)	
(3)	SW3RN-SNETP and SW6RN-SN	IFTP (Ver 004) car	not coexist	
(0)	To make SW2RN SNETD and SV			
	IN TRACE SWORN-SINE IF AILUS			
	SNETP Ver. UUB or later. (Refer t	o Section3.4.6 (2) f	or details.)	
(4)	For DOCPRNP and LADDERP, in	nstall the DOCPRN	P or LADDERP	
	software package that meets the	operating environm	ent.	
	You cannot install and operate S\	//3RN-[][]P and SV	V20RN-[][]P	
	together.			
	Operating Environment	DOCPRNP	LADDERP	
	Office 97 (Word 97, Excel 97)	SW3RN-DOCPRNP	SW3RN-LADDERP	
	Office 2000(Word 2000, Excel 2000)	SW20RN-DOCPRNP	SW20RN-LADDERP	



(1) Installing GSV13P, GSV22P, GSV43P, GSV51P, CAMP, DOSCP, SNETP and/or DOCPRNP



From preceding page	
InstallShield Wizard Welcome to the InstallShield Wizard for Sw3RN-GSV22P The InstallShield® Wizard will install SW3RN-GSV22P on your computer. To continue, click Next. (Book Next) Cancel	9) The left screen will soon appear. Click [Next >].
InstallShield Wizard Customer Information Please enter your information. Please enter your name and the name of the company for whom you work. User Name: MITSUBISHI Company Name: MITSUBISHI ELECTRIC CORPORATION InstallEHeed (Back Next> Cancel	10) Type user name and company name, and click [Next >].
	 11) Choose the installation destination. The installation destination directory defaults to "C:\Program Files". When not changing it, click [Next >]. When changing it, click [Browse].
To next page	







(2) Installing LADDERP 1) Power on the personal computer and start Windows NT/98/2000. Insert the CD-ROM disc into the CD-ROM drive. Insert CD-ROM disk. Ó 2) Click [Start] on the taskbar and move the cursor to Documents [Settings]. 🔯 Control Panel Click [Control Panel]. 🛐 🗧 <u>S</u>ettings 🔄 Printers 🔺 🐴 Iaskbar & Start Menu. 💦 Eind S Folder Options. 🖉 <u>H</u>elp Active Desktop <u> 문</u>un.. Click here. 🖄 Log Off Administrator. Shut Down. 🔀 Start 🛛 🏉 🖆 💆 👰 3) The Control Panel window appears. 🔯 Control Panel - 🗆 × Double-click "Add/Remove Programs" from Control <u>File Edit View Go Favorites H</u>elp e යා Undo Panel. • È Up X Cut Paste De Ŧ • Address 🐼 Control Panel Double-click this icon. **Control Panel** କ୍ଷ B ŪŠ ę. Accessibility Options Add/Remo Program Console Date/Time Select an icon to view its description. Ħ 4 Aa 4) The "Add/Remove Programs Properties" screen Add/Remove Programs Prop ? × appears. Install/Uninstall Windows NT Setup To install a new program from a floppy disk or CD-ROM drive, click Install Click [Install...]. 쎑 Install. Communication of the automatically removed by Windows. To remove a program or to modify its installed components, select it from the list and click Add/Remove 0 Maruo editor Microsoft Internet Explorer 4.0 Microsoft Music Control Microsoft Music Control Microsoft Uffice 37, Professional Edition Microsoft Utilok Express Microsoft Wallet Microfouch TouchWare 5.4 SW3RN-CAMPE SW3RN-DOCPRNPE • OK Cancel To next page

3.2 Registered lcons

Installing GSV13P, GSV22P, GSV43P, GSV51P, CAMP, LADDERP, DOSCP, SNETP and/or DOCPRNP registers the icons as shown below. (1) GSV13P

(2) GSV22P

(3) GSV43P

New Office Document				
Open Office Document				
Programs	Accessories			
► Favorites	Startup +			
Documents	Windows NT Explorer			
Settings	Administrative Foots (Common)			間 Backup
Eind ▶	Startup	(⊂) SW3RN-CAMP ►		🗣 Install T🔳 Montior
JIKST	Microsoft Excel	SW3RN-DOCPRNP >	โฒ ร₩38N.DOSCP ►	REProgram Editor
	D microsoft word		SW3RN-GSV13P	Servo Data Setting
S Log Off Administrator			SW3RN-GSV43P	P Test
Shut Down			SW3RN-LADDERP	
🖬]		G SW3RN-SNETP →	1

(4) GSV51P

New Office Document				
Programs	Accessories			
* Favorites	Gen Startup Kommand Prompt			
Documents	Windows NT Explorer			
Eettings	Len Administrative Tools (Common)			
Eind	Startup	G SW3RN-CAMP ►	1	間 Backup 튁 Install
er State	Microsoft Excel	SW3RN-DOCPRNP	© SW3RN-DOSCP →	Contine Montion
E un			SW3RN-GSV13P ■ SW3RN-GSV22P	Project Management
Sop 🖄 Log Off Administrator			SW3RN-GSV43P	El System Setting
Shut Down			SW3RN-LADDERP	
🏦 Start 🛛 🏉 🚰 🖉 🦉				

(5) CAMP

(6) LADDERP (a) SW3RN-LADDERP

(b) SW20RN-LADDERP

	New Office Document		
	Programs	Em Accessories Final Accessories	
	* Favorites	🛱 Startup 🔸	Help for Batch Monitor
		🔀 Command Prompt	Help for Ladder Circuit Editor
	Documents	Windows NT Explorer	Help for LADDER EDITOR
	Z-	Administrative Tools (Common) 🕨	Help for Print Utility
	EUS Settings	InstallShield Professional 2000 🔸	LADDER EDITOR Batch Monitor
ion	Eind	Startup	LADDER EDITOR Ladder Circuit Editor
tat	TON THIS	SW20RN-D0CPRNP >	IADDER EDITOR Print Utility
rks	A Help	Microsoft Excel	LADDER EDITOR Text Convertor Utility
No	-	Microsoft Word	DDERP V Baladder Editur ToolBar
Ē	<u>烹</u> — <u>B</u> un	Lee Swarn cova	
g	~		/13P /
6	🖄 Log Off Administrator		
Ĕ	S		(61D)
≥	Shut Down	Sw3BN-SNFT	
	Start 🛛 🌮 🛃 🕸 📗		

(7) DOSCP

New Office D	ocument				
Open Office I	Document				
Programs	, and a contract of the second secon	cessories +			
* F <u>a</u> vorites	ہ 📻 Sta 🏙 Cor	rtup •			
Documents	► 🔍 Wi	ndows NT Explorer			
Settings	.⊜Adi • @ins	ministrative Tools (Common) 🔸 tallShield Professional 2000 🔸			
	Jen Sta	rtup • /nRNC-GSVE •	SW3RN-CAMP		
Part A Felb	🔊 Mic 1977 Mic	crosoft Excel crosoft Word	SW3RN-DOCPRNP >	🖻 SW3RN-DOSCP 🔹 🕨	🜌 Digital Osilo Scope
L E un					
🦉 🖉 Log Off Admir	nistrator			G SW3RN-GSV43P → G SW3RN-GSV51P	
둘 🔊 Shut Down				SW3RN-LADDERP >	
🔀 Start 🖉 🏕 🚰	10]			<u> </u>	

(8) SNETP

(a) When SNETP is installed in the environment of Windows NT/98

	٩	Windows Update								
B	22.0	Programs	•	Accessories	-					
<u>o</u> s	$\widehat{}$	Documents	•	SWnRNC-GSV	ŀ	SW3RN-CAMP	•			
ş	勵	Settings	•	Internet Explore Outlook Express	E	SW3RN-DOCPRN		SW3PN-DOSCP	•	
P.	2	Search	•		<u>.</u>	5110101C 057		SW3RN-GSV13P	•	
S 200	۲	Help						SW3RN-GSV22P SW3RN-GSV43P	+	
ğ	-	Run						SW3RN-GSV51P	•	
Ĕ		Shut Down						SW3RN-LADDERP SW3RN-SNETP		SSCNET Communication Parameter Setting
2		1 × 4 × ×	_				_		1.0	SSCNET Communication Task Start

(b) When SNETP is installed in the environment of Windows 2000

(9) DOCPRNP (a) SW3RN-DOCPRNP

	New Office Document				
	Programs +	Accessories			
	* Favorites	Startup +			
	Documents •	Windows NT Explorer			
e	Settings	InstallShield Professional 2000			
tatior	🔊 Eind 🔸	SWnRNC-GSVE	SW3RN-CAMP ►	~	
Vorks	Alp Help	Microsoft Excel	SW3RN-DOCPRNP	Printing Utility for MS-EXCEL Conversion	
NTV	2 Bun				
smop	🖉 Log Off Administrator				
Win	By Shut Down				
	Start 🖉 🖆 💋 🥺				

(b) SW20RN-DOCPRNP

New Office Document				
Programs +	Accessories			
Favorites	Startup			
Documents	Windows NT Explorer Administrative Tools (Common)			
Settings	InstallShield Professional 2000			
🚊 🕥 Eind 🔹	SWnRNC-GSVE	SW20RN-DOCPRNP 🕨	Printing Utility for MS-EXCEL Conversion	
Vorks Helb	Microsoft Excel	L©J SW3RN-CAMP → C©J SW3RNC-GSVE →	Printing Utility for MS-WORD Conversion	
💑 🔔 Log Off Administrator				
Shut Down				
🏦 Start 🛛 🍘 🛃 👰 🚽				

3.3 Created System Directories

Installing GSV13P, GSV22P, GSV43P, GSV51P, SNETP, DOSCP, CAMP, DOCPRNP, LADDERP and/or GSVHELP creates the directories as shown below.
3.4 Operating Instructions

3.4.1 Precautions for Using SW3RN-GSV43P

To use GSV43P, you need to make environment setting in the "Config.nt" or "Config.sys" file.

Before using GSV43P, always set the "Config.nt" or "Config.sys" file for the following data.

If you do not make the setting in the "Config.nt" or "Config.sys" file, GSV43P will not run properly.

(1) For Windows NT/2000

Windows NT/2000 requires the following data in the "Config.nt" file. "Config.nt" is found in the following location.



Depends on the drive set at install

Config.nt

EMM=RAM
dos=high, umb
device=%SystemRoot%\system32\himem.sys
FILES=20
devicehigh=%SystemRoot%\system32\ansi.sys

(2) For Windows 98

Windows 98 requires the following data in the "Config.sys" file. "Config.sys" is found in the following location.

		- 2	
Drive C	Со	nfig.s	sys

• Config.sys

DOS=HIGH,UMB device=c:\windows\himem.sys device=c:\windows\EMM386.EXE RAM devicehigh=c:\windows\command\ansi.sys

REMARKS

When Windows 98 is used, there are some personal computer models where the EMS driver will not be installed properly.

If the EMS driver is not installed properly, starting program edit will display the following screen and edit will not start.

In that case, add an option to the EMS driver of Config.sys to enable edit to start.

Describe an M[] option after the EMS driver and reboot the personal computer.

(In [], set any numeral between 1 and 14.)

(Example) device=c:\windows\EMM386.EXE RAM M5



3.4.2 Precautions for Using SW20RN-DOCPRNP

(1) Security levels of Word and Excel

To use SW20RN-DOCPRNP, the security level must be set on Word or Excel. If the security level setting is "High", you cannot use SW20RN-DOCPRNP. Before using SW20RN-DOCPRNP, set the security level of Word or Excel to other than "High."



POINT		
If the Word o	or Excel security level sett	ting is "High" at start of SW20RN-
DOCPRNP,	SW20RN-DOCPRNP will	not start properly as described below
and cannot b	be used.	
In such a ca	se, change the Word or E	xcel security level setting to other than
"High" and re	estart SW20RN-DOCPRN	IP.
Refer to Sec	tion 3.4.2 for the way to c	hange the security level.
V	Vord screen	Excel screen
🗃 DOCPRNP(Word) - M	icrosoft Word	Microsoft Excel
Eile Edit View Insert I	ormat <u>T</u> ools T <u>a</u> ble <u>W</u> indow <u>H</u> elp	Eile Edit View Insert Format Iools Data Window Help
) 🗈 🛍 🗠 - 🍓 100% - 😨 👋	□ ☞ ■ @ ◎ ▲ ♡ % № 亀 い - 魯 Σ ⋟ タ 雌
L	1 • • • • • • • 2 • • • • • • • 3 • • • •	
1		
•		
1		
: ,		

(2) Antivirus software

It has been reported that when the "Norton AntiVirus 2000" antivirus software of Symantec Corporation has been installed in the personal computer, specifying Office 2000 as a control feature from an external program will run the micro virus check software, one of the "Norton AntiVirus 2000" functions, making Office 2000 uncontrollable from other programs. Hence, when "Norton AntiVirus 2000" has been installed, SW20RN-DOCPRNP

that controls Office 2000 externally cannot be booted.

The following are the corrective actions for the above problem.

- (a) When it is not necessary to make virus checks Uninstall "Norton AntiVirus 2000".
- (b) When it is necessary to make virus checks
 Remove only the micro virus check software of "Norton AntiVirus 2000".
 In this case, the other virus checks are performed.

For more information on the micro virus check software problems of "Norton AntiVirus 2000", refer to the home page of Microsoft Corporation or Symantec Corporation.

- Microsoft Corporation
- http://support.microsoft.com/support/kb/articles/Q246/0/18.ASP?LN=EN-US& SD=gn&FR=0&qry=q246018&rnk=1&src=DHCS_MSPSS_gnSRCH&SPR= WRD20
- Symantec Corporation http://service1.symantec.com/SUPPORT/nav.nsf/df0a595864594c86852567a c0063608c/8cabdef3ea6d2861882567fd006ea11d?OpenDocument



• How to remove only micro virus check software from "Norton AntiVirus 2000"

3.4.3 Precautions for operation under Windows 98

When the GSV application is used under Windows 98, the following phenomena may occur.

Follow the description for the countermeasure.

(1) The color inside the GSV application window is not displayed correctly. The color inside the GSV application window may not be displayed correctly with the maximum setting of the graphics hardware accelerator. In this case, change the graphics accelerator setting to a basic setting.



 Double click on "Display" in the Control Panel. The "Display Properties" window is displayed. Select the "Settings" tab and click on [Advanced...].



- Select the "Performance" tab and change the "graphics hardware acceleration" setting to a basic one and click on [OK].
 - Close "Display Properties" and reset the PC.
 - * If necessary, recover the original setting of the graphics hardware acceleration.

(2) During data sampling on the digital oscilloscope (DOSCP) screen, a sampling failure may occur.

If one of the following operation is performed during sampling, a sampling failure may occur. (Accordingly there is disorder in the displayed waveform. In the figure below, a spike is displayed in the speed command.)

- Another application is started.
- The function screen of GSV[][]P is started.
- Programs or parameters are uploaded or downloaded with GSV[][]P.

If there is a failure in the sampling data even when the above operation is not performed, terminate the other applications.

🖾 Digital Oscillo Scope				. 🗆 🛛
File(E) Action(A) Edit(E) View(V)	Help(<u>H)</u>			
66 * * * * * *	** ©! ??]		
SERVO DIGITAL STORAG	ESCOPE		SCREEN	
			FRIEZE	
				B
				C II
			HORIZOHTAL	₹_+
			[ā (€))3 a[-()) i
			SCROLL	
			VERTICAL SKIP	EED
			BIT DATA OH	
			1 M9032	0
A-B; an., A-T; an.,	B-T; un	nawi -	2 м9033	1
CH1 3000 CHE 3000 CHB	300 CH# 300		3 1-In-position	1
WORD DATA CH			4 M9034	0
1 2-Speed command	3937	വല	5 1-Cmd. In-positio	0
2 1-Position comman	58	ഷധ	6 1-Start Accpt.Flg	1
3 4-Speed command	3937	വല	7 1-Auto.Dec.Flg	0
4 FT	8249788	കഥ	8 M2001	1
Ready			CPU : A173UH OFF	LINE //

3.4.4 Simultaneous execution of SW3RN-GSV[][]P and SW6RN-GSV[][]P

SW3RN-GSV[][]P and SW6RN-GSV[][]P cannot be used simultaneously. If the operation described below is attempted, the following error message is displayed in response to the GSV[][]P started later and startup fails.

Servo Da	ata Setting 🛛 🗙
G	The system file is in error.
$\overline{\mathbf{v}}$	[DSRP.]: System file read failed.
	[RMDY.]: Perform the operation again. If the error still occurs, exit all GSV applications then restart the application. If even so the error occurs, maybe the system file is false. Install the GSV again.
	<u>OK</u>

[Operation]

- Starting SW3RN-GSV[][]P and SW6RN-GSV[][]P simultaneously from menu
- CAMP (Cam Data Setting) for executing both JUMP icons to SW3RN-GSV[][]P and SW6RN-GSV[][]P



Do not perform above operations.

SW3RN-GSV[][]P and SW6RN-GSV[][]P cannot be executed simultaneously. Start either application only.

3.4.5 Simultaneous execution of SW3RN-DOSCP and SW6RN-DOSCP

You cannot use SW3RN-DOSCP and SW6RN-DOSCP together. If the following operation is performed, DOSCP booted later is not started and is ignored.

[Operation]

- Starting SW3RN-DOSCP and SW6RN-DOSCP simultaneously from menu
- CAMP (Cam Data Setting) for executing both JUMP icons to SW3RN-GSV[][]P and SW6RN-GSV[][]P



Do not perform above operations.

SW3RN-DOSCP and SW6RN-DOSCP cannot be executed simultaneously. Start either application only.

3.4.6 Precautions for using SNETP

- SW3RN-SNETP or SW6RN-SNETP (Ver. 00A) is in use (SW6RN-GSV[][]P (Ver. 00A) is in use) In any of the following cases, corresponding SNETP may result in a communication error, disabling normal communication.
 - SNETP of an early version is used to perform a communication method that is not supported.
 - Two or more copies of SNETP of different versions are installed.
 - Both SW3RN-SNETP and SW6RN-SNETP are installed.
 - Windows NT Windows 98 and Windows 2000 are installed in a single PC and SNETP of different versions is installed in each drive.
 - Windows NT Windows 98 and Windows 2000 are installed in a single PC and SW3RN-SNETP and SW6RN-SNETP are installed in each drive.

Only one version of corresponding SNETP may be installed into one personal computer.

Install only one copy of SNETP of the best version according to the desired communications means (SSCNET, USB, 232C).

The communications means supported by each version of SNETP is shown in the table 3.1.

	Version	For A motion SW3RN-GSV[][]P	For Q motion(Q172/Q173) SW6RN-GSV[][]P	SW3RN-DOSCP*
Ver.00A Communication can be ma		Communication can be made	Q motion is not supported (a communication error is caused).	Can be used. (However, a communication error is caused upon Q172/Q173.)
SW3RN-SNETP	Ver.00B	OVER SSCINET.	Communication can be made over SSCNET.	
	Ver.00E or later	Communication can be made over SSCNET or via RS232C.	Communication can be made over SSCNET.	Can be used
SW6RN-SNETP	Ver.00A	Communication can be made over SSCNET.	Communication can be made over SSCNET or via RS232C or USB.	

Table 3.1 The communications means supported by each version of SNETP

*: SW3RN-DOSCP is only for communication over SSCNET.

IMPORTANT

When updating SW6RN-GSV[][]P (to Ver. 00B or later), refer to "3.7 Updating Instructions and Procedures" and update one set of SW6RNC-GSVE. In this case, SW6RN-SNETP is updated (to Ver. 00B or later). Refer to the instructions in (2) on the next page.

(2) Precautions for use of SW6RN-SNETP Ver. 00B or later(a) Coexistence of SNETP

SW6RN-SNETP Ver. 00B or later can be installed to coexist with SW3RN-SNETP.

Software Packages	Compatible Version	Remarks
SW6RN-SNETP	Ver. 00B or later (Ver. 00A cannot coexist)	Dedicated to the Q motion controller. Incompatible with the applications de- signed for A motion controllers.
SW3RN-SNETP	Any version ^{*1}	

Table 3.2 SNETP Versions That Can Coexist

*1: For SW3RN-SNETP Ver. 00G or earlier, however, there are precautions for installation/uninstallation. Refer to "Section 3.4.6 (2) (d)".

(b) GSV applications compatible with SW6RN-SNETP Ver. 00B or later Table 3.3 indicates the GSV applications compatible with SW6RN-SNETP Ver. 00B or later.

Table 3.3 GSV applications compatible with SW6RN-SNETP Ver. 00B or later

Software Packages	Compatible Version	Remarks
SW6RN-GSV13P	Ver OOB er leter	When using any of the packages given
SW6RN-GSV22P	Ver.00B of later	on the left, use SW6RN-SNETP Ver.
SW6RN-DOSCP	Ver.00A or later	00B or later.

- (c) Concurrent execution of SW3RN-SNETP and SW6RN-SNETP You cannot use SW3RN-SNETP and SW6RN-SNETP together.
 - 1) When those programs are started in order of SW3RN-SNETP and SW6RN-SNETP, SW6RN-SNETP booted is ignored.
 - 2) When the programs are started in order of SW6RN-SNETP and SW3RN-SNETP (Ver. 00H or later), SW3RN-SNETP booted is ignored.
 - 3) When the programs are started in order of SW6RN-SNETP and SW3RN-SNETP (Ver. 00G or earlier), SW3RN-SNETP displays the following message and does not start properly. Exit from SW3RN-SNETP.



(d) Precautions for installation, uninstallation and updating when SW6RN-SNETP (Ver. 00B or later) and SW3RN-SNETP (Ver. 00G or earlier) coexist

When SW6RN-SNETP Ver. 00B or later and SW3RN-SNETP Ver. 00G or earlier coexist, note that there are restrictions on installation and uninstallation.

- When installing SW3RN-SNETP (Ver. 00G or earlier) into the personal computer where SW6RN-SNETP (Ver. 00B or later) has been installed
 After installing SW3RN-SNETP, always set the driver setup again.
- 2) When uninstalling SW3RN-SNETP in the personal computer where SW6RN-SNETP (Ver. 00B or later) and SW3RN-SNETP (Ver. 00G or earlier) coexist
 - Uninstall "SW6RN-SNETP", "SW3RN-SNETP" and "SSCNET communication driver" once.
- After uninstallation, reinstall SW6RN-SNETP and set the driver setup. 3) When updating SW3RN-SNETP to Ver. 00H or later in the personal computer where SW6RN-SNETP (Ver. 00B or later) and SW3RN-SNETP (Ver. 00G or earlier) coexist
 - Refer to Section 3.4.6 (2) (f) 2 1).
- (e) Precautions for uninstalling SW6RN-SNETP (Ver. 00B or later) or SW3RN-SNETP (Ver. 00H or later)

Uninstall SW6RN-SNETP Ver. 00B or later or SW3RN-SNETP Ver. 00H or later as described below.

- 1) When SNETP does not coexist
 - a) When uninstalling SW6RN-SNETP (Ver. 00B or later) Uninstall "SW6RN-SNETP" and "SSCNET communication driver".
 - b) When uninstalling SW3RN-SNETP (Ver. 00H or later) Uninstall "SW3RN-SNETP" and "SSCNET communication driver".
- 2) When SW6RN-SNETP (Ver. 00B or later) and SW3RN-SNETP (Ver. 00H or later) coexist
 - a) When uninstalling SW6RN-SNETP (Ver. 00B or later) only Uninstall "SW6RN-SNETP" only. (Do not uninstall the "SSCNET communication driver".)
 - b) When uninstalling SW3RN-SNETP (Ver. 00H or later) only Uninstall "SW3RN-SNETP" only. (Do not uninstall the "SSCNET communication driver".)
 - c) When uninstalling both SW6RN-SNETP (Ver. 00B or later) and SW3RN-SNETP (Ver. 00H or later) Uninstall "SW6RN-SNETP", "SW3RN-SNETP" and "SSCNET communication driver".

- (f) Precautions for updating SNETP
 - Update SW6RN-SNETP to Ver. 00B or later or SW3RN-SNETP to Ver. 00H or later as described below.
 - 1) When updating SW6RN-SNETP (Ver. 00A) to Ver. 00B or later After uninstalling "SW6RN-SNETP", install new SW6RN-SNETP and perform a driver setup.
 - 2) When updating SW3RN-SNETP (Ver. 00G or earlier) to Ver. 00P or later a) When SNETP does not coexist
 - After uninstalling "SW3RN-SNETP", install new SW3RN-SNETP and perform a driver setup.
 - b) When SW3RN-SNETP coexists with SW6RN-SNETP (Ver. 00B) After uninstalling "SW3RN-SNETP" and "SSCNET communication driver", install new SW3RN-SNETP and perform a driver setup.
 - c) When updating SW6RN-SNETP (Ver. 00B or later) After uninstalling "SW6RN-SNETP", install new SW6RN-SNETP. A driver setup is not necessary.
 - d) When updating SW3RN-SNETP (Ver. 00H or later) After uninstalling "SW3RN-SNETP", install new SW3RN-SNETP. A driver setup is not necessary.

3.5 Uninstallation

This section gives the way to delete GSV13P, GSV22P, GSV43P, GSV51P, CAMP, LADDERP, DOSCP, SNETP and/or DOCPRNP from the hard disk.



To next page

3. INSTALLATION AND UNINSTALLATION



3.6 Operating Manual SW3RNC-GSVHELPE

After installing the SW3RNC-GSVHELPE Operating Manuals, you can browse them by performing the following operation.

(1) You can browse any of the operating manuals from the "Help" menu of the corresponding software package.



(2) Each operating manual is a file in the Windows help format (extension is HLP). Any operating manual can be browsed by directly double-clicking the corresponding file from Explorer or like.

(Refer to Section 3.3 for the folder where SW3RNC-GSVHELPE has been installed.)

3.7 Updating Instructions and Procedures

This section describes the instructions and operating procedures for updating SW3RNC-GSVE to Ver. 00H.

The versions of the SW3RNC-GSVE Ver. 00H packages are indicated in Table 3.4.

Туре	Version	Product Name
SW3RN-GSV13P	00E	Transfer/assembly software
SW3RN-GSV22P	00E	Automatic machine software
SW3RN-GSV43P	00D	Machine tool peripheral software
SW3RN-GSV51P	00B	Special-purpose robot software
SW3RN-CAMP	00E	Cam data creation software
SW3RN-LADDERP	00F	Ladder editing software (For Office 97)
SW20RN-LADDERP	00B	Ladder editing software (For Office 2000)
SW3RN-DOCPRNP	00H	Document printing software (For Office 97)
SW20RN-DOCPRNP	00D	Document printing software (For Office 2000)
SW3RN-DOSCP	00E	Digital oscilloscope software
SW3RN-SNETP	00J	SSCNET communication system software

Table 3.4 Package Definitions of SW3RNC-GSVE Ver. 00H

When updating, update one set of the above packages.

- (1) Updating performed when only SW3RNC-GSVE has been installed
 - When performing updating in the personal computer where the SW3RNC-GSVE Ver. 00F or earlier (the one in Table 3.4 or earlier) version has been installed.





(2) Updating performed when SW6RN-GSV and SW3RN-GSV coexist

|--|

(1) For the installation/uninstallation operation associated with updating, refer to "3.1 Installation" and "3.5 Uninstallation".

SSCNET COMMUNICATION DRIVERS 4.

4.1 SSCNET Communication Driver Setup Procedure

To make SSCNET communication in Windows NT/98, you need to perform SSCNET communication driver setup.

Perform the setup work of the SSCNET communication drivers in the [SSCNET Communication Driver Setup] window of SNETP.

ΟK

Cancel

Detail



POINT				
 You need not set the drive interface board to the person Always click [Cancel] in the window. When only RS232C core When SSCNET communic (When only the offline for When there is no interface In either of the following construction is not performed because When the A30CD-PCF board is used in the Wire (3) The interface boards and environment. 	er when you do sonal compute ne "SSCNET C nmunication is unication is not unction for pro ace card or inte ases, an SSC of compatibilit interface card ndows 2000 er interface card	o not fit the inter a described communication used gram edit, etc. erface board NET community with the plug and the A10C nvironment. s can be used	erface card or below. Driver Setup" is used) cation driver s and play func D-PCF interfact in the followin	etup stion. ce g
	Windows 98	Windows NT	Windows 2000	
A30BD-PCF interface board	0	0	×	
A10BD-PCF interface board	0	0	0	
A30CD-PCF interface board	0	0	0	
			Usable: \bigcirc	
			Unusable: \times	

4.1.1 When using the A30CD-PCF interface card

SSCNET Communication Driver Setup SSCNET I/F Type OK Image: Signal Stress	 The SSCNET Communication Driver Setup window appears. *You need not make the setting when you use RS232C communication or do not use SSCNET communication. Click [Cancel] to exit from SSCNET Communication Driver Setup. <for nt="" windows=""> Choose "A30CD-PCF Card Type" and click [Detail].</for>
	<for 98="" windows=""> Choose "A30CD-PCF Card Type" and click [OK]. *Detail setting is not necessary for Windows 98.</for>
For Windows NT For Windows 98 To 4)	
Detail X IRQ Level: 9 Memory Base Address: C0000 I/0 Port Address: 330 SSCNET Com. CH. ND.is 0 fixation OK Cancel	 2) Check and set the free areas of IRQ Level, Memory Base Address and I/O Port Address. Click [OK]. *For the way to check the free areas, refer to "4.2 How to Check the System Resources".
SSCNET Communication Driver Setup SSCNET I/F Type Image: A 300D-PCF C A30BD-PCF C A30CD-PCF C A30BD-PCF Card Type Board Type(ISA) Donly the RS232C communication click Detail [Cancel] in case of use. Detail	3) Click [OK].
To next page	

This section provides the SSCNET communication driver setup procedure for use of the interface card.

4. SSCNET COMMUNICATION DRIVERS

From preceding page	
Change SSCNET Communication Driver Image: A straight of the set of	 4) The left dialog box appears. <for nt="" windows=""> When the interface card is already loaded Click [Yes]. The personal computer is restarted. </for> When the interface card is not yet loaded Click [No]. Choose "Shut Down" in the Start menu to power off the personal computer. After making sure that the power is off, load the interface card into the personal computer.
	<for 98="" windows=""> Click [Yes]. The personal computer is restarted. After Windows 98 has restarted, load the interface card into the personal computer. IRQ Level, Memory Base Address and I/O Port Address are automatically set by the plug and play function of Windows 98.</for>
	5) After Windows NT/98 has restarted, choosing and

5) After Windows NT/98 has restarted, choosing and clicking [Programs]-[SWnRNC-GSVE]-[SW3RNC-GSVE]-[SW3RN-SNETP]-[Start SSCNET Task] in the Start menu makes SSCNET communication ready to start.

4.1.2 When using the A30BD-PCF interface board

This section provides the SSCNET communication driver setup procedure for use of the interface board.



4. SSCNET COMMUNICATION DRIVERS

From preceding page	
Change SSCNET Communication Driver Image: Communication Dri	5) The left dialog box appears. <for nt="" windows=""> Click [No]. Choose "Shut Down" in the Start menu to power off the personal computer. After making sure that the power is off, confirm the switch setting of the interface board and load the interface board into the personal computer. After Windows NT has restarted, choosing and clicking [Programs]-[SWnRNC-GSVE]-[SW3RNC- GSVE]-[SW3RN-SNETP]-[Start SSCNET Task] in the Start menu makes SSCNET communication ready to start.</for>
	<for 98="" windows=""> Click [No]. Choose "Shut Down" in the Start menu to power off the personal computer. After making sure that the power is off, confirm the switch setting of the interface board and load the interface board into the personal computer. Restart Windows 98 and register the SSCNET communication drivers. For the registration of the SSCNET communication driver, refer to "4.4 Registering the SSCNET Communication Drivers".</for>

4.1.3 When using the A10BD-PCF interface board

1) The SSCNET Communication Driver Setup window appears. Choose "A10BD-PCF Board Type" and click [Detail]. SSCNET Communication Driver Setup *1:You need not make the setting when you use the - SSCNET I/F Type OK A10BD-PCF interface board. C A30CD-PCF C A30BD-PCE A10BD-PCF Card Type Board Type(ISA) Board Type(PCI) Cancel *2:You need not make the setting when you use Only the RS232C communication click [Cancel] in case of use. RS232C communication or do not use SSCNET communication. Click [Cancel] to exit from SSCNET Communication Driver Setup. 2) The left dialog box appears. <For Windows NT> Click [No]. Choose "Shut Down" in the Start menu to power off the personal computer. After making sure that the power is off, confirm the Change SSCNET Communication Driver switch setting of the interface board and load the To validate the new setting, the computer must be rebooted. Do you want to reboot computer immediately? interface board into the personal computer. <u>'</u>!\ Yes <u>N</u>o <For Windows 98> Click [No]. Choose "Shut Down" in the Start menu to power off the personal computer. After making sure that the power is off, confirm the switch setting of the interface board and load the interface board into the personal computer. 3) After Windows NT/98 has restarted, choosing and clicking [Programs]-[SWnRNC-GSVE]-[SW3RNC-GSVE]-[SW3RN-SNETP]-[Start SSCNET Task] in

This section provides the SSCNET communication driver setup procedure for use of the interface board.

the Start menu makes SSCNET communication

ready to start.

4.2 How to Check the System Resources

This section explains how to check the free areas of the system resources such as IRQ Level, Memory Base Address and I/O Port Address.

(1) For Windows NT

Refer to the Windows NT diagnostics and check the free areas of the system resources.



POINT

The resource use state may be described in the manual of the personal computer.

In this case, refer to the manual.

(2) For Windows 98

Check the free areas of the system resources from the My Computer icon on the desktop.



POINT

The resource use state may be described in the manual of the personal computer. In this case, refer to the manual.

4.3 Setting the Interface Board

4.3.1 Setting the A30BD-PCF Interface Board

This section describes the switch setting of the interface board.



(1) Reset switch (SW1)

Turn on the reset switch (SW1) to reset the interface board. During communication, do not press the reset switch as it will shut off communication.

If proper communication cannot be made, reset the interface board with the reset switch and then make communication.

(2) Interrupt level (SW2, SW3)

Set the identification number (IRQ level) used by the Operating System to recognize the interface board.

When setting the interrupt level, set to ON only one switch whose level does not overlap the interrupts of the other ISA bus extension boards, and set all other switches to OFF.

Note that the settings of SW2 and SW3 should be the same.

SW2, SW3		Definition	Default	Remarks
	1	IRQ10 enable	OFF	
	2	IRQ11 enable	OFF	OFF : Invalid
	З	IRQ12 enable	OFF	ON : Valid
	4	IRQ15 enable	OFF	

(3) Setting the occupied addresses (SW4)Set the addresses occupied by the interface board on the personal computer.

SW4		Definition	Default	Remarks
	1	Not used	OFF	Always set to OFF.
	2	Controller setting line 1 (CON1 port)	OFF	
∞∎_	3	Controller setting line 2 (CON2 port)	OFF	Always set to ON.
	4	Address selection 1	OFF	Set the occupied addresses.
ມ∎	5	Address selection 2	OFF	For details, refer to the
4	6	Address selection 3	OFF	following Table 4.1.
	7	8/16 bit width selection	OFF	Set the bit width of the ISA bus. Set to OFF (16 bits). OFF : 16 bits ON : 8 bits
	8	IRQ switching	OFF	Always set to ON.

 Address selection 1 to 3 (SW4-4 to 6) and occupied regions One interface board occupies a 16K byte region. Table 4.1 Occupied Address Regions

Table 4.1 Occupied Address Regions

	Switch	1	Occupied Address Region	CON1 Port Region	CON2 Port Region
4	5	6	First to last	First to last	First to last
OFF	OFF	OFF	C0000h to C3FFFh	C0000h to C0FFFh	C1000h to C1FFFh
OFF	OFF	ON	C4000h to C7FFFh	C4000h to C4FFFh	C5000h to C5FFFh
OFF	ON	OFF	C8000h to CBFFFh	C8000h to C8FFFh	C9000h to C9FFFh
OFF	ON	ON	CC000h to CFFFFh	CC000h to CCFFFh	CD000h to CDFFFh
ON	OFF	OFF	D0000h to D3FFFh	D0000h to D0FFFh	D1000h to D1FFFh
ON	OFF	ON	D4000h to D7FFFh	D4000h to D4FFFh	D5000h to D5FFFh
ON	ON	OFF	D8000h to DBFFFh	D8000h to D8FFFh	D9000h to D9FFFh
ON	ON	ON	DC000h to DFFFFh	DC000h to DCFFFh	DD000h to DDFFFh

4.3.2 Setting the A10BD-PCF Interface Board

This section explains the switch setting of the A10BD-PCF interface board.



(1) Board ID setting switch (SW1) When there are two or more PCI type A10BD-PCF's, set the ID numbers to identify the respective A10BD-PCF's.

SW2, SW3		Definition	Default	Remarks
	1	Board ID bit 0 (BDID0)	OFF	Set the ID number. For details, refer to the following
or√153⊄	2	Board ID bit 1 (BDID1)	OFF	
	3	Board ID bit 2 (BDID2)	OFF	Table 4.2.
	4	Controller setting (MODE)	ON	Always set to ON.

1) Board ID bit choices 0 to 2 (SW1-1 to 3) and ID numbers

Table 4.2 ID Numbers	Table	4.2	ID	Numbers
----------------------	-------	-----	----	---------

Sw	itch Numb	ers	
1	2	3	Board ID
BDID0	BDID1	BDID2	
OFF	OFF	OFF	0
ON	OFF	OFF	1
OFF	ON	OFF	2
ON	ON	OFF	3

(2) Reset switch (SW2)

Turn on the reset switch (SW2) to reset the A10BD-PCF.

Do not press the reset switch during communication since doing so will shut off communication.

If normal communication cannot be made, press the reset switch to reset the A10BD-PCF and then start communication.

(3) LED display

Indicates the status of the A10BD-PCF. • When the A10BD-PCF is normal: Flicker

- When the A10BD-PCF is abnormal: On or off
- LED1 For CON1 port

- LED2 For CON2 port
- (4) Allotment between Board IDs and SSCNET CH No.

Bord ID	CON1 port	CON2 port
0	CH.0	CH.1
1	CH.2	CH.3
2	CH.4	CH.5
3	CH.6	CH.7

4.4 Registering the SSCNET Communication Drivers

When using the A30BD-PCF interface board on Windows 98 to make SSCNET communication, register the SSCNET communication drivers in the following procedure. (The following operation is not required when using the A30BD-PCF interface card and A10BD-PCF interface board.)

Since the A30BD-PCF interface board is not compatible with the plug and play function of Windows 98, you need to register the SSCNET communication drivers to Windows 98 after installing SNETP and setting up the SSCNET communication drivers. (When reinstalling SNETP, the SSCNET communication drivers are already registered and need not be registered again.)

Register the SSCNET communication drivers in the following procedure.



4. SSCNET COMMUNICATION DRIVERS



- (1) Registering the fast refresh driver

4. SSCNET COMMUNICATION DRIVERS



To next page





(2) Registering the CH. 0 transient driver





- (3) Registering the CH. 0 cyclic driver
 - Register the CH. 0 cyclic driver in the procedure as in "(2) Registering the CH. 0 transient driver". Note that "SNETP DRIVER (Cyclic CH. 0)" should be chosen as Model in the hardware maker and model selection window.



\bigcirc	Select the manufactu	rer and model of your hardware.
\sim	If your hardware is no Disk.If your hardware hardware type.	t listed, or if you have an installation disk, click Have is still not listed, click Back, and then select a different
<u>M</u> anufa	oturers:	Models:
Mitron Mitsuba Mitsubi Mitsubi Mitsum MKEP:	a Corp. Still shi Electronics	SNETP DRIVER (Cyclic CH.1) SNETP DRIVER (Fast resh: A306D-PCF Board SNETP DRIVER (Transient CH.0) SNETP DRIVER (Transient CH.0) SSCNET Card 36H1324 (A30CD-PCF Card)
		Have Disk
		< <u>B</u> ack Next > Cancel

1) When not using CH. 1, you need not make this setting.

Proceed to "(6) Adjusting the fast refresh driver". Register the CH. 1 transient driver in the procedure as in "(2) Registering the CH. 0 transient driver". Note that "SNETP DRIVER (Transient CH. 1)" should be chosen as Model in the hardware maker and model selection window.

(5) Registering the CH. 1 cyclic driver



1) When not using CH. 1, you need not make this setting.

Proceed to "(6) Adjusting the fast refresh driver". Register the CH. 1 cyclic driver in the procedure as in "(2) Registering the CH. 0 transient driver". Note that "SNETP DRIVER (Cyclic CH. 1)" should be chosen as Model in the hardware maker and model selection window.
(6) Adjusting the fast refresh driver

Adjust the IRQ and occupied addresses of the SSCNET communication drivers to the data assigned in detail setting of "SSCNET Communication Driver Setup".

The following example assumes that the following assignment was made in detail setting of "SSCNET Communication Driver Setup".

(Example)

L.

• IRQ..... 11 Memory Base Address...... D0000

Detail				×
IRQ Level:		11	•	
- Memory Ba	ase Address	SSCNET (CON1	Com. CH. NO. CON2	ОК
🔽 1st	D0000 💌	CH.0	CH.1	Cancel
🗖 2nd	v	CH.2	CH.3	Hele
🗖 3rd	7	CH.4	CH.5	map
🗖 4th	V	CH.6	CH.7	
SSCNET Communication Driver				

1) Choose and right-click the My Computer icon on the desktop.

Click [Properties] from the pop-up menu.

Open Mu Com The pop-up menu appears. Explore Find. Map Network Drive. Disconnect Network Drive. My Docu Create Shortcut Rename 6 Interr 2) The "System Properties" window appears. System Properties ? X Click [Device Manager]. General Device Manager Hardware Profiles Performance Choose and double-click "Other devices". View devices by type C View devices by connection You can confirm the interface board drivers Computer ٠ CDROM Disk drives registered in (1) to (5). SNETP DRIVER (Transient CH. 0) Display adapters
 Display adapters
 Floppy disk controllers
 Hard disk controllers • SNETP DRIVER (Cyclic CH. 0) Keyboard
 Monitors
 Mouse
 Mouse
 Mouse SNETP DRIVER (Transient CH. 1)* SNETP DRIVER (Cyclic CH. 1)* r retwork adapters Other devices - 3 SNETP DRIVER (Cyclic CH.0) - 9 SNETP DRIVER (Cyclic CH.1) - 9 SNETP DRIVER (Transient CH.1 - 9 SNETP DRIVER (Transient CH.1 - 9 SNETP DRIVER (Transient CH.1 - 9 SNETP DRIVER (Transient CH.1) SNETP DRIVER (Fast Fresh: A30BD-PCF Board) *Displayed only when CH.1 is registered in driver SNETP DRIVER (Cyclic CH.1) SNETP DRIVER (Fast Fresh: A30BD-PCF Board) registration. SNETP DRIVER (Transient CH.0) SNETP DRIVER (Transient CH.1) When CH. 1 is not used, these drivers are not registered and are not shown. Refresh R<u>e</u>move Pri<u>n</u>t. Properties Here, choose "SNETP DRIVER (Fast Fresh: A30BD-OK Cancel PCF Board)" and click [Properties]. To next page





(7) Adjusting the CH. 0 transient driver

Adjust this driver as in the adjustment of the fast refresh driver.

1) As in the adjustment of the fast refresh driver, System Properties ? × choose Properties from the My Computer icon to General Device Manager Hardware Profiles Performance show the "System Properties" window. O View devices by <u>c</u>onnection View devices by type Click [Device Manager]. 🖳 Computer 庄 골 CDROM ٠ Choose and double-click "Other devices". Disk drives Choose "SNETP DRIVER (Transient CH. 0)" and Display adapters E - Floppy disk controllers Hoppy disk controllers Hard disk controllers Keyboard Monitors Mouse High Network adapters click [Properties]. Uther devices SNETP DRIVER (Cyclic CH.0) SNETP DRIVER (Cyclic CH.1) SNETP DRIVER (Fast Fresh : A30BD-PCF Board) SNETP DRIVER (Transient CH.0) SNETP DRIVER (Transient CH.0) 😨 Other devices • Refresh R<u>e</u>move Pri<u>n</u>t. Properties OK Cancel 2) The "SNETP DRIVER (Transient CH. 0)" Properties" SNETP DRIVER (Transient CH.0) Properties ? × window appears. General Driver Resources Click [Resources]. SNETP DRIVER (Transient CH.0) Choose "Memory range" to highlight it and click □ Use automatic settings [Change Setting...]. Setting based on: Basic configuration 0 -Setting Resource type Memory Range 000DA000 - 000DAFFF Change Setting... Conflicting device list No conflicts -ΟK Cancel 3) The "Memory Range" window appears. Edit Memory Range ? × Type "D0000-D0FFF" in the Value field and click Enter the memory range you would like to set for this device [OK]. You may either enter a specific range and the nearest valid range will be selected automatically, or you may select a range using the arrows. *Set the same "Memory range" value as set in the fast refresh driver. *Section 4.4 (12) provides the SSCNET **Communication Driver Setup Memory Base** ⊻alue: 00000000 • 00000FFF ÷ Address and driver memory range setting table. Conflict information The setting you have chosen conflicts with the following devices: Use it for your reference. SNETP DRIVER (Fast Fresh : A30BD-PCF Board) OK Cancel To next page

From preceding page	
Conflict Warning Image: Selected conflicts with another device. To select a different resource setting, click No. To continue, click Yes. Image: Test Image: Selected conflicts with another device.	4) The "Conflict Warning" dialog box appears, but click [Yes].
SNETP DRIVER (Transient CH.0) Properties ? × General Driver Resources P SNETP DRIVER (Transient CH.0) Use automatic settings Setting based on: Basic configuration 0 Resource type Setting Memory Parage 000D0000 - 000D0FFF Conflicting device list Memory Range 000D0000 - 000D0FFF used by: SNETP DRIVER (Fast Fresh: A308D-PCF Board) . OK Cancel	5) Click [OK].
Creating a Forced Configuration Image: Configuration Image: Solution of the set of th	 6) The "Creating a Forced Configuration" dialog box. Click [Yes]. This finishes the adjustment of the CH. 0 transient driver.

(8) Adjusting the CH. 0 cyclic driver

Adjust the CH. 0 cyclic driver in the procedure as in "(7) Adjusting the CH. 0 transient driver".

Note that "SNETP DRIVER (Cyclic CH. 0)" should be selected in the "System Properties" window.

Set the memory range for CH. 0 cyclic driver adjustment to the same value as the memory range of the CH. 0 transient driver.

- (9) Adjusting the CH. 1 transient driver
 - When not using CH. 1, you need not adjust the CH. 1 transient driver. Proceed to "(11) Restarting the personal computer".
 - (a) Adjust the CH. 1 transient driver in the procedure as in "(7) Adjusting the CH. 0 transient driver".

Note that "SNETP DRIVER (Transient CH. 1)" should be selected in the "System Properties" window.

- (b) Set the memory range for CH. 1 transient driver adjustment to the value set for the CH. 0 memory range plus "1000".
 (example)
 When the CH. 0 value is "000D0000-000D0FFF", set the CH. 1 transient driver value to "000D1000-000D1FFF".
- (10) Adjusting the CH. 1 cyclic driver

When not using CH. 1, you need not adjust the CH. 1 cyclic driver. Proceed to "(11) Restarting the personal computer".

- (a) Adjust the CH. 1 cyclic driver in the procedure as in "(7) Adjusting the CH.
 0 transient driver".
 Note that "SNETP DRIVER (Cyclic CH. 1)" should be selected in the
- "System Properties" window.(b) Set the memory range for CH. 1 cyclic driver adjustment to the same value
- as the memory range of the CH. 1 transient driver.
- (11) Restarting the personal computer After all settings are over, click [Close] in "System Properties" to close the window.

Click [Shut Down] in the Start menu to restart the personal computer.

(12) Memory Base Addresses of SSCNET Communication Driver Setup and Memory Ranges of Drivers

Memory Base	Memory Range of	Memory Ranges of Transient/Cyclic Driver		
Address	Refresh Driver	CH.0	CH.1	
C0000	C0000h to C1FFFh	C0000h to C0FFFh	C1000h to C1FFFh	
C4000	C4000h to C5FFFh	C4000h to C4FFFh	C5000h to C5FFFh	
C8000	C8000h to C9FFFh	C8000h to C8FFFh	C9000h to C9FFFh	
CC000	CC000h to CDFFFh	CC000h to CCFFFh	CD000h to CDFFFh	
D0000	D0000h to D1FFFh	D0000h to D0FFFh	D1000h to D1FFFh	
D4000	D4000h to D5FFFh	D4000h to D4FFFh	D5000h to D5FFFh	
D8000	D8000h to D9FFFh	D8000h to D8FFFh	D9000h to D9FFFh	
DC000	DC000h to DDFFFh	DC000h to DCFFFh	DD000h to DDFFFh	

4.5 Stopping the SSCNET Communication Driver

When removing the interface board or interface card on Windows NT/98 from the personal computer, you need to stop the SSCNET communication driver. (When removing the interface card on Windows 98, use the plug and play function of Windows. You need not perform the following operation.) (1) For Windows NT





- 8) Close the Control Panel and choose [Shut Down] in the Start menu to reboot the personal computer. The SSCNET communication driver stops after rebooting.
- Before removing the interface card or interface board, choose [Shut Down] in the Start menu to power off the personal computer.



S	vstem Properties
	General Device Manager Hardware Profiles Performance
	Floppy disk controllers Hard disk controllers Keyboard Monitors Mouse SNETP DRIVER (Cyclic CH.0) SNETP DRIVER (Cyclic CH.1) SNETP DRIVER (Cyclic CH.1) SNETP DRIVER (Transient CH.0) SNETP DRIVER (Transient CH.1) SNETP DRIVER (Transient CH.1) SNETP DRIVER (Transient CH.1) SNETP DRIVER (Transient CH.1) SNETP System devices
	Properties Refresh Remove Print

From preceding page

- 5) The "System Properties" window reappears. Perform the operations in steps 3) and 4) also for the other devices.
 - SNETP DRIVER (Transient CH. 0)
 - SNETP DRIVER (Cyclic CH. 0)
 - SNETP DRIVER (Transient CH. 1)*
 - SNETP DRIVER (Cyclic CH. 1)*
 *Perform operations only when CH. 1 has been registered in driver registration.
- 6) Click [OK] to close the "System Properties" window.

- Choose "Shut Down" in the Start menu to reboot the personal computer. The SSCNET communication driver stops after rebooting.
- 8) Before removing the interface board, choose [Exit Windows] in the Start menu to power off the personal computer.

4.6 Communication Settings Using GSV[][]P

Communication settings must be made to start RS232C/SSCNET communication. To make communication settings, use the "Communication Setting" button in the "Communication Setting" menu or communication dialog box of GSV[][]P.

(1) When using the "Communication Setting" menu of GSV[][]P



- 二× 副 低 新 配 計 記 評 語 第 Click here.	1) Click [Communication] from the Jump button of GSV[][]P.
Communication - GSV22P Help(H) Transfer Data Batch Servo Setting Data "System Setting "Servo Setting Data "Axis Data "Axis Data "Parameter Block "Limit Switch Setting SFC Program SFC Program "Control Code(SFC, F/FS, G) Click here. "Text(F/FS, G) Servo Program Cam Data Motion Device (#0 to #8191)	2) The communication dialog box appears. Click [Com. Setting].
Communication Setting X Com. Task ID NO.	 3) The communication settings dialog box appears. 4) Set RS232C/SSCNET communication. Refer to Help (SW3RNC-GSVHELPE) for the way to set RS232C/SSCNET communication.

(2) When using the communication dialog box

4.6.1 Communication errors

Any of the errors as indicated in Tables 4.3 and 4.4 may occur during communication started after communication settings. In this case, take action in accordance with Table 4.3 or Table 4.4 (1) For SSCNET communication

Table 4.3 Communication Error during SSCNET Communication

Error Code	Error Message	
-255	Install Image: Constraint of the const	

(2) For RS232C communication

Error Code	Error Message
-255	Install X A communication error occurred (Err. Code=-255) [DSRP.]: A communication error was detected in the communication driver. [RMDY.]: 1. Check whether the communication cable is connected properly. 2. Check whether the motion controller power is on. 3. Check whether the motion controller is faulty. If it is faulty, reset once using the reset key. 4. Check whether the operating system can make SSCNET communication. If communication cable may be faulty.
6 and 16130	Install Image: Constraint of the second state of the second
	[Action] When making RS232C communication, uninstall old SNETP (refer to Section 3.5), then install and use SW3RN-SNETP Ver. 00D or later.

Table 4.4 Communication Errors during RS232C Communication

POINT

If a communication error occurs at any point during communication using RS232C, check the power saving setting of the personal computer. If the RS232C item is valid in the power saving setting, make it invalid since an error may occur during communication. For details of the power saving setting, refer to the manual of the personal computer used.

5. TROUBLESHOOTING

Remedies for trouble are described in this section. Refer to this section when you are in trouble.

5.1 GSV[][]P or DOSCP does not start or it is terminated during operation

No	Phenomenon	Corresponding Version	Cause and remedy
1	When monitor, DOSCP or other application is started from the menu, the following message describing failure to find "sscpdr.dll" is displayed. • Windows NT/2000 Program@ditracevelunable to Locate DLL Program@ditracevelunable to Locate DLL Program. Program P	SW3RN- GSV[][]P SW3RN- DOSCP	 SNETP is not installed. Even if communication with the CPU is not made actually, SNETP must be installed. Refer to section 3.4.6(1) to install the best SNETP. If communication is made only with the A motion, install SW3RN-SNETP. A list of applications for communication with the CPU is displayed. The following applications cause the phenomenon described to the left. (Applications other than those listed below operate without SNETP.) GSV[][]P : Monitor, communication, program editor, install, mechanical system editor, test, backup, servo data setting (for writing to servo amplifier)
2	The communication starting procedure causes the following error and termination of the process.	SW3RN- GSV[][]P	SW3RN-DOSCP: Digital oscilloscope 2) The PATH specified as the long name has been described in AUTOEXEC.BAT. *: Long name: Folder name of 9 or more characters Describe the SNETP PATH before the PATH specified as the long name, and always add "%PATH%" before the part where the long name has been specified. It is not required if it has already been described. (Example) • Before change SET PATH="C:\Program_Files\ABC;" ^(*1) SET PATH=%PATH%;C:\PROGRA~1\Snetp; ^(*2) •
			SET PATH= <u>%PATH%;</u> "C:\Program_Files\ABC;" *: Always described the (wiggly line) part. (*1): Long name PATH (*2): SNETP PATH

5.2 If communication over SSCNET or via RS232C fails with GSV[][]P

Refer to the description of "Remedy" in the error message basically for the action to be taken upon a communication error.

If the problem is not removed, refer to the table below for corrective action.

No.	Phenomenon	Cause and remedy
	Communication error "-255" occurred during communication over SSCNET.	1) The actually connected channel does not agree with the setting. Refer to section 4.6 "Communication setting with GSVI II
1	Install X Image: A communication error occurred.[Err. Code=-255] [DSRP.]: A communication error was detected in the communication driver. [RMDY.]: 1. Check whether the communication cable is connected properly. 2. Check whether the motion controller power is on. 3. Check whether the motion controller power is on. 3. Check whether the motion controller power is on. 4. Check whether the motion controller as faulty. If it is faulty, reset once using the reset key. 4. Check whether the operating system can make SSCNET communication. If communication cannot still be started, the SSC card/board or communication cable may be faulty.	 JP" to check the SSCNET communication channel. 2) The SSCNET communication driver is not set up correctly. Set up the SSCNET communication driver to perform communication over SSCNET. Refer to section 4.1 "SSCNET communication driver setup procedure" to set up the driver.
2	Communication error "6" occurred during communication via RS232C. Communication A communication error occurred.[Err. Code=6) [DSRP.]: Access to the outside of the shared memory range was made. [RMDY.]: After closing the screen in error once, start and execute again. If the error recurs, close all applications which are making communication, such as the peripheral software package and digital oscilloscope, then terminate the SSCNET communication task, start the communication task, and start and execute the application again.	 When SW3RN-SNETP (Ver. 00C or earlier) is in use, the phenomenon described on the left may occur. Refer to "3.7 Updating Instructions and Procedures" and update one set of SW3RNC-GSVE. When it is not updated, follow the remedy since the possible cause is any of the following 1) to 5). 1) SNETP of an early version is used. Uninstall the early version and install the new version of SNETP that supports the A motion. (*1) 2) Two or more copies of SNETP of different versions are installed. Uninstall all copies of SNETP. If any system directory (file) of SNETP remains after they are uninstalled, delete using Explorer or the like. Next, install only one copy of SNETP of a version that supports the A motion. (*1) 3) Both SW3RN-SNETP and SW6RN-SNETP Ver.00A are installed in one PC. Uninstall both SW3RN-SNETP and SW6RN-SNETP Ver.00A are installed in one PC. Uninstall all copies of SNETP of different versions is installed in each drive. Uninstall all copies of SNETP and SW6RN-SNETP Ver.00A are installed in one PC and SNETP of different versions is installed in each drive. Uninstall all copies of SNETP then install SNETP of a single version that supports the A motion to both the Windows 98 Windows NT and Windows 2000 are installed in one PC and SW3RN-SNETP and SW6RN-SNETP of a single version that supports the A motion to both the Windows 98 Windows NT and Windows 2000 are installed in one PC and SW3RN-SNETP and SW6RN-SNETP Ver.00A are installed in each drive. Uninstall all copies of SNETP then install SNETP of a single version that support the A motion to both the Windows 98 Windows NT and Windows 2000 are installed in one PC and SW3RN-SNETP and SW6RN-SNETP Ver.00A are installed in each drive. Uninstall all copies of SNETP then install SNETP of a single version that support the A motion to both the Windows 98 Windows NT and Windows 2000 drives. (*1)
3	Communication error "16130" occurred during communication via RS232C. Monitor A communication error occurred (Err. Code=16130) [DSRP.]: An internal error occurred. [RMDY.]: Execute again. If the error recurs, close the screen in error once, then start and execute again.	

*1: Refer to section 3.4.6(1) to install the best SNETP.

If communication is made only with the A motion, install SW3RN-SNETP.

No.	Phenomenon	Cause and remedy
4	Communication error "10" occurred during communication over SSCNET. Install A communication error occurred (Err. Code=10) [DSRP.]: The communication task ID number is not set properly. [RMDY.]: Set a correct communication task ID number in the "SSCNET communication parameter setting" window of the SSCNET communication software (SWnRN-SNETP), and restart the peripheral software package. DK	1) SW6RN-SNETP was booted. Exit from SW6RN-SNETP and boot SW3RN-SNETP.

*1: Refer to section 3.4.6(1) to install the best SNETP.

If communication is made only with the A motion, install SW3RN-SNETP.

No.	Phenomenon	Cause and remedy
1	Communication error "50" or "51" occurred. Cannot communicate with the CPU (50). C K Cannot communicate with the CPU (51). Communication error "10" occurs.	 SW3RN-SNETP is not booted. Boot SW3RN-SNETP. SW6RN-SNETP (Ver. 00B or later) has been booted.
2	Cannot communicate with the CPU (10).	Exit from SW6RN-SNETP (Ver. 00B or later) and boot SW3RN-SNETP.
3	Communication error "-255" occurs.	 When SW3RN-DOSCP is in use, the phenomenon described on the left may occur. Refer to "3.7 Updating Instructions and Procedures" and update one set of SW3RNC-GSVE. After that, boot SW3RN-DOSCP. When SW3RN-DOSCP is in use, follow the remedy since the possible cause is any of the following 1) to 5). 1) SNETP of an early version and install the new version of SNETP that supports the A motion. (*1) 2) Two or more copies of SNETP. If any system directory (file) of SNETP remains after they are uninstalled, delete using Explorer or the like. Next, install only one copy of SNETP of a version that supports the A motion. (*1) 3) Both SW3RN-SNETP and SW6RN-SNETP are installed in one PC. Uninstall both SW3RN-SNETP and SW6RN-SNETP and install either one again. (*1) 4) Windows 98, Windows NT and Windows 2000 are installed in each drive. Uninstall all copies of SNETP of different versions is installed in each drive. Uninstall all copies of SNETP and SW6RN-SNETP and single version that supports the A motion (*1) 5) Windows 98, Windows NT and Windows 2000 drives. (*1) 5) Windows 98, Windows NT and Windows 2000 are installed in one PC and SW3RN-SNETP and SW6RN-SNETP of a single version that supports the A motion to both the Windows 98, Windows NT and Windows 2000 drives. (*1) 5) Windows 98, Windows NT and Windows 2000 are installed in one PC and SW3RN-SNETP and SW6RN-SNETP of a single version that supports the A motion to both the Windows 98, Windows NT and Windows 2000 are installed in one PC and SW3RN-SNETP and SW6RN-SNETP of a single version that supports the A motion to both the Windows 98, Windows NT and Windows 2000 drives. (*1)

5.3 If communication over SSCNET fails with DOSCP

5. TROUBLESHOOTING

No.	Phenomenon	Cause and remedy
4	Communication error "12" occurs. Cannot communicate with the CPU (12). O K	The SSCNET communication driver is not set up correctly. To perform communication over SSCNET, set up the SSCNET communication driver. To do this, refer to section 4.1 "SSCNET communication driver setup procedure."

*1: Refer to section 3.4.6(1) to install the best SNETP.

If communication is made only with the A motion, install SW3RN-SNETP.

5.4 If no sampling data is obtained from DOSCP

No.	Phenomenon	Cause and remedy
	No sampling data is obtained. (The waveform is not detected.)	The SSCNET communication driver is not set up correctly.
		To perform communication over SSCNET, set up the
1		SSCNET communication driver.
		To do this, refer to section 4.1 "SSCNET communication
		driver setup procedure."

5.5 When SNETP is booted, "Not enogh memory" error occurs

No.	Phenomenon	Cause and remedy
1	When SNETP is booted, "Not enogh memory" error occur	s. When SNETP is booted in the order of SW6RN-SNETP Ver. 00B or later and SW3RN-SNETP Ver. 00G or earlier, SW3RN-SNETP displays the error given on the left and does not start. Exit from SW3RN-SNETP.



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