# FR-F 500 

## Frequency Inverter

## Installation Manual

## FR-F 540L EC

## About this Manual

The texts, illustrations, diagrams, and examples contained in this manual are only intended as aids to help explain the installation, set-up, and starting of the frequency inverter FR-F 540L EC.

If you have any questions concerning the programming and operation of the equipment described in this manual, please contact your relevant sales office or department (refer to back of cover). Current information and answers to frequently asked questions are also available through the Internet (www.mitsubishi-automation.com).

MITSUBISHI ELECTRIC EUROPE B.V. reserves the right to make changes both to this manual and to the specifications and design of the hardware at any time without prior notice.

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| :--- | :--- | :--- |
| Version |  |
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## Safety instructions

## For qualified staff only

This manual is only intended for use by properly trained and qualified electrical technicians who are fully acquainted with automation technology safety standards. All work with the hardware described, including system design, installation, set-up, maintenance, service and testing, may only be performed by trained electrical technicians with approved qualifications who are fully acquainted with the applicable automation technology safety standards and regulations. Any operations or modifications of the hardware and/or software of our products not specifically described in this manual may only be performed by authorised Mitsubishi staff.

## Proper use of equipment

The devices of the FR-F series are only intended for the specific applications explicitly described in this manual. Please take care to observe all the installation and operating parameters specified in the manual. The design, manufacturing, testing and documentation of these products have all been carried out in strict accordance with the relevant safety standards. Under normal circumstances the products described here do not constitute a potential source of injury to persons or property provided that you precisely observe the instructions and safety information provided for proper system design, installation and operation. However, unqualified modification of the hardware or software or failure to observe the warnings on the product and in this manual can result in serious personal injury and/or damage to property. Only accessories specifically approved by MITSUBISHI ELECTRIC may be used with the frequency inverter FR-F 540L EC. Any other use or application of the products is deemed to be improper.

## Relevant safety regulations

All safety and accident prevention regulations relevant to your specific application must be observed in the system design, installation, setup, maintenance, servicing and testing of these products.

The regulations listed below are particularly important. This list does not claim to be complete; however, you are responsible for knowing and applying the regulations applicable to you:

- VDE-/EN Standards
- VDE 0100
(Regulations for electrical installations with rated voltages up to $1,000 \mathrm{~V}$ )
- VDE 0105
(Operation of electrical installations)
- VDE 0113
(Electrical systems with electronic equipment)
- EN 50178
(Configuration of electrical systems and electrical equipment)
- Fire prevention regulations
- Accident prevention regulations
- VBG No. 4 (electrical systems and equipment)

General safety information and precautions
The following safety precautions are intended as a general guideline for using the frequency inverter together with other equipment. These precautions must always be observed in the design, installation and operation of all control systems.

## DANGER:

- Observe all safety and accident prevention regulations applicable to your specific application. Installation, wiring and opening of the assemblies, components and devices may only be performed with all power supplies disconnected.
- Assemblies, components and devices must always be installed in a shockproof housing fitted with a proper cover and protective equipment.
- Devices with a permanent connection to the mains power supply must be integrated in the building installations with an all-pole disconnection switch and a suitable fuse.
- Check power cables and lines connected to the equipment regularly for breaks and insulation damage. If cable damage is found, immediately disconnect the equipment and the cables from the power supply and replace the defective cabling.
- Before using the equipment for the first time check that the power supply rating matches that of the local mains power.
- Residual current protective devices pursuant to DIN VDE Standard 0641 Parts 1-3 are not adequate on their own as protection against indirect contact for installations with frequency inverter systems. Additional and/or other protection facilities are essential for such installations.
- EMERGENCY OFF facilities pursuant to VDE 0113 must remain fully operative at all times and in all control system operating modes. The EMERGENCY OFF facility reset function must be designed so that it cannot cause an uncontrolled or undefined restart.
- You must also implement hardware and software safety precautions to prevent the possibility of undefined control system states caused by signal line cable or core breaks.


## CAUTION:

All relevant electrical and physical specifications must be strictly observed and maintained for all the frequency inverters in the installation. The load used should be a three-phase induction motor only. Connection of any other electrical equipment to the inverter output may damage the equipment.

## Safety warnings

In this manual special warnings that are important for the proper and safe use of the products are clearly identified as follows:
DANGER:
Personnel health and injury warnings. Failure to observe the precautions described
here can result in serious health and injury hazards.

Personnel health and injury warnings. Failure to observe the precautions described here can result in serious health and injury hazards.

CAUTION:
Equipment and property damage warnings. Failure to observe the precautions described here can result in serious damage to the equipment or other property.

## 1 Introduction

This Installation Manual includes a brief summary of the main specifications of the FR-F 500L frequency inverters, which should be sufficient to enable experienced users to install and configure the inverter. For further information on the functions and parametrization please refer to the Instruction Manual of the frequency inverter FR-F 500L. This Installation Manual is intended exclusively as an installation and setup guide and a brief reference. It does not replace the main product manual.

### 1.1 General Description

The inverters of the FR-F 540L EC series are available with outputs from 75 k to 530 k . The device is designed for the connection to $3 \sim 380$ to $480 \mathrm{~V}(50 / 60 \mathrm{~Hz})$. The output frequency ranges from 0.5 to 120 Hz .

## Features of the frequency inverters

- Communication ability and networking

For the integration in an automation plant a serial interface RS485 is included as standard equipment. Through this interface up to 31 inverters can be linked up. Open communications with standardised industrial bus systems as Profibus/DP, DeviceNet or CC-Link can be realised easily via optional interface cards.

- Compatibility with a lot of new applications
- PID Control

The inverter can be used to exercise process control, e.g. flow rate for pumps.

- Stop function selection (terminal MRS)

This function is used to select the stopping method (deceleration to a stop or coasting).

- Switch-over to commercial power supply
- Large number of protective functions for safe operation
- Automatic restart after instantaneous power failure The inverter can be started without stopping the motor (with the motor coasting).
- Built-in overcurrent protection
- Retry function after alarm occurence
- Automatic torque boost


## 2 Specifications

### 2.1 Model Specifications

| Type |  |  | FR-F 540L |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | 75 k | 90 k | 110 k | 132 k | 160 k | 185 k | 220 k | 280 k | 375 k | 450 k | 530 k |
| $\begin{aligned} & \text { H } \\ & \frac{0}{3} \\ & 0 \end{aligned}$ | Rated motor capacity [kW] ${ }^{1}$ | 120\% Overload capacity ${ }^{(6)}$ | 75 | 90 | 132 | 160 | 185 | 220 | 250 | 315 | 400 | 530 | 530 |
|  |  | 150\% Overload capacity | 75 | 90 | 110 | 132 | 160 | 185 | 220 | 280 | 375 | 450 | 530 |
|  | Rated current [A] | 120\% Overload capacity ${ }^{(6)}$ | 144 | 180 | 260 | 302 | 360 | 432 | 477 | 610 | 750 | 1010 | 1010 |
|  |  | 150\% Overload capacity | 144 | 180 | 216 | 260 | 302 | 360 | 432 | 547 | 722 | 866 | 1010 |
|  | Rated output capacity [kVA] | 120\% Overload capacity ${ }^{(6)}$ | 110 | 137 | 198 | 230 | 274 | 329 | 417 | 464 | 571 | 770 | 770 |
|  |  | 150\% Overload capacity | 110 | 137 | 165 | 198 | 230 | 274 | 329 | 417 | 550 | 660 | 770 |
|  | Overload capacity ${ }^{2}$ | 120\% Overload capacity | $120 \%$ of rated motor capacity for $0.5 \mathrm{~s} ; 110 \%$ for 1 min (max. ambient temperature $40^{\circ} \mathrm{C}$ ); typical e.g. for pumps and fans |  |  |  |  |  |  |  |  |  |  |
|  |  | 150\% Overload capacity | $150 \%$ of rated motor capacity for 0.5 s; $120 \%$ for 1 min (max. ambient temperature $50^{\circ} \mathrm{C}$ ); typical e.g. for Conveyor belts and Centrifuges |  |  |  |  |  |  |  |  |  |  |
|  | Rated input AC voltage ${ }^{(3)}$ |  | 3 -phase, OV up to power supply voltage |  |  |  |  |  |  |  |  |  |  |
|  | Frequency range |  | $0.5-120 \mathrm{~Hz}$ |  |  |  |  |  |  |  |  |  |  |
|  | Control method |  | V/f control or optimum excitation control |  |  |  |  |  |  |  |  |  |  |
|  | Modulation control |  | Sine elevated PWM, Soft PWM |  |  |  |  |  |  |  |  |  |  |
|  | Carrier frequency |  | $0.7 \mathrm{kHz} / 1 \mathrm{kHz} / 2.5 \mathrm{kHz}$, (user adjustable) |  |  |  |  |  |  |  |  |  |  |
| $\begin{aligned} & \stackrel{\rightharpoonup}{\mathrm{O}} \\ & \stackrel{1}{ } \end{aligned}$ | Power supply voltage |  | 3-phase, 380-480V AC, $-15 \% /+10 \%$ |  |  |  |  |  |  |  |  |  |  |
|  | Permissible AC voltage fluctuation |  | $323-528 \mathrm{~V}$ AC at $50 / 60 \mathrm{~Hz}$ |  |  |  |  |  |  |  |  |  |  |
|  | Power supply frequency |  | $50 / 60 \mathrm{~Hz} \pm 5 \%$ |  |  |  |  |  |  |  |  |  |  |
|  | Rated input capacity $[\mathrm{kVA}]^{4}$ | 120\% Overload capacity ${ }^{(6)}$ | 110 | 137 | 198 | 230 | 274 | 329 | 364 | 464 | 571 | 770 | 770 |
|  |  | 150\% Overload capacity | 110 | 137 | 165 | 198 | 230 | 274 | 329 | 417 | 550 | 660 | 770 |
|  | Power loss <br> [W] | 120\% Overload capacity ${ }^{(6)}$ | 2250 | 2750 | 4120 | 4800 | 5550 | 6750 | 8590 | 11250 | 9000 | 10600 | 10600 |
|  |  | 150\% Overload capacity | 2250 | 2750 | 3375 | 4120 | 4800 | 5550 | 6750 | 8590 | 11250 | 9000 | 10600 |

## NOTE

The rating $120 \%$ is available with serial marking "type02" only (shipping from the middle of 2003).

Please observe the notes on page 10 !

| Type |  |  | FR-F 540L |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | 75 k | 90 k | 110 k | 132 k | 160 k | 185 k | 220 k | 280 k | 375 k | 450 k | 530 k |
|  | Frequency setting value | Analog | $0.015 \mathrm{~Hz} / 50 \mathrm{~Hz}$ (connecting terminal $2: 12$ Bit / $0-10 \mathrm{~V}$; 11 Bit / 0-5V, connecting terminal 1:12 Bit /-10-+10V; 11 Bit / $-5-+5 \mathrm{~V}$ ) |  |  |  |  |  |  |  |  |  |  |
|  |  | Digital | 0.01 Hz |  |  |  |  |  |  |  |  |  |  |
|  | Frequency precision |  | $\pm 0.2 \%$ of max. output frequency (temperature range $25^{\circ} \mathrm{C} \pm 10^{\circ} \mathrm{C}$ ) during analog input; $\pm 0.01 \%$ of max. output frequency during digital input |  |  |  |  |  |  |  |  |  |  |
|  | Voltage/frequency characteristic |  | Base frequency adjustable from 0 to 120 Hz ; constant torque or variable torque selectable; optional flexible flexible 5 -Point-V/f-characteristics |  |  |  |  |  |  |  |  |  |  |
|  | Acceleration/deceleration time |  | $0 ; 0.1$ to 3600s individual settings |  |  |  |  |  |  |  |  |  |  |
|  | Acceleration/deceleration characteristics |  | Linear or S-form course, user selectable |  |  |  |  |  |  |  |  |  |  |
|  | DC-braking |  | Braking time and braking moment adjustable, operation frequency: $0-120 \mathrm{~Hz}$, operation time: $0-10 \mathrm{~s}$, Voltage: $0-30 \%$ |  |  |  |  |  |  |  |  |  |  |
|  | Torque boost |  | Manual and automatic torque boost |  |  |  |  |  |  |  |  |  |  |
|  | Stall prevention |  | Responds treshold 0-150\%, user adjustable, also via analog input |  |  |  |  |  |  |  |  |  |  |
|  | Motor protection |  | Electronic motor protection relay (rated current user adjustable) |  |  |  |  |  |  |  |  |  |  |
|  | Frequency setting values | Analog input | $0-5 \mathrm{~V}$ DC, $0-10 \mathrm{~V}$ DC, $0- \pm 10 \mathrm{~V}$ DC, $0 / 4-20 \mathrm{~mA}$ |  |  |  |  |  |  |  |  |  |  |
|  |  | Digital | From control panel or optional circut board |  |  |  |  |  |  |  |  |  |  |
|  | Input signals | Starting signal | Individual selection of forward / reverse run Start signal self retaining input. |  |  |  |  |  |  |  |  |  |  |
|  |  | Speed selection | Up to 7 speed settings can be selected (each speed can be preset from 0 to 120 Hz ). The current speed can be changed via the control panel during operation. |  |  |  |  |  |  |  |  |  |  |
|  |  | 2nd/3rd acceleration/ deceleration time | 0 to 3600 seconds <br> (Acceleration and deceleration time can be set individually.) |  |  |  |  |  |  |  |  |  |  |
|  |  | JOG operation | Jog operation via control panel or special JOG-terminal |  |  |  |  |  |  |  |  |  |  |
|  |  | Current input selection | Frequency setting via current input signal 0/4 to 20mA DC |  |  |  |  |  |  |  |  |  |  |
|  |  | Automatic restart | Selection of whether automatic restart is made or not after an instantaneous power failure |  |  |  |  |  |  |  |  |  |  |
|  |  | External thermal input | Stopping the inverter with an externally mounted thermal relay |  |  |  |  |  |  |  |  |  |  |
|  |  | MT-HC connection | Inverter operation enable input and instantaneous power failure detection input |  |  |  |  |  |  |  |  |  |  |
| $\begin{array}{\|l} \hline 0 \\ \vdots \\ \hline \mathbf{0} \\ \hline \end{array}$ |  | External DC dynamic brake | External input for DC dynamic braking start |  |  |  |  |  |  |  |  |  |  |
| $\stackrel{\stackrel{0}{0}}{\stackrel{0}{0}}$ |  | PID control | Select PID control |  |  |  |  |  |  |  |  |  |  |
| $\begin{array}{\|l\|} \hline 0 \\ 0 \\ \hline 0 \\ \hline 0 \end{array}$ |  | PU <-> External operation | Switch between the operating modes "PU" and "External" |  |  |  |  |  |  |  |  |  |  |
| 荅 |  | PU operation external interlock | External interlock switch-over of PU operation |  |  |  |  |  |  |  |  |  |  |
|  |  | Output stop | Instant cutoff of inverter output (frequency and voltage) |  |  |  |  |  |  |  |  |  |  |
|  |  | Error reset | The error indication (alarm signal) is reset with the reset of the protective function. |  |  |  |  |  |  |  |  |  |  |
|  | Output signals | Operation state | 5 five output types can be selected: <br> inverter running, instantaneous power failure (undervoltage), frequency detection, 2nd frequency detection, in PU operation, overload warning, electronic thermal relay pre-alarm, zero current detection, PID lower limit, PID upper limit, PID forward run, PID reverse run, commercial power supply-inverter switchover MC1-2-3, operation ready, fan trouble, overheat fin pre-alarm (open-collector-output) |  |  |  |  |  |  |  |  |  |  |
|  |  | Alarm functions | Relay output ... contactor (230V AC / 0.3A, 30V DC / 0.3A) Open collector output ... error message through alarm code (4 bits) |  |  |  |  |  |  |  |  |  |  |
|  |  | Analog signal or pulse train | One of the following output types can be selected: output frequency, motor current (constant or peak value), output voltage, frequency setting value, operation speed, converter output voltage (constant or peak value), regenerative brake duty, electronic thermal relay load rate, input power, output power, load meter, pulse train output ( 1440 Hz / full scale), or analog output ( $0-10 \mathrm{~V}$ DC). |  |  |  |  |  |  |  |  |  |  |

Please observe the notes on page 10 !

| Type |  |  | FR-F 540L |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | 75 k | 90 k | 110 k | 132 k | 160 k | 185 k | 220 k | 280 k | 375 k | 450 k | 530 k |
| 을 | Displayed on control panel (FR-PU04/ FR-DU04) | Operating state | Output frequency, motor current (constant or peak value), output voltage, frequency setting value, operation speed, overload, converter output voltage (constant or peak value), electronic thermal relay load rate, input power, output power, load meter, cumulative power ON time, current operation time, cumulative power and motor load rate. |  |  |  |  |  |  |  |  |  |  |
|  |  | Alarm display | Error details are displayed after a protective function is activated. Up to 8 error codes can be stored. |  |  |  |  |  |  |  |  |  |  |
|  | Additional displays on control panel FR-PU04 | Operating state | Signal state of input and output terminals. |  |  |  |  |  |  |  |  |  |  |
|  |  | Alarm display | Output voltage, output current, output frequency, cumulative power ON time before activation of protective function |  |  |  |  |  |  |  |  |  |  |
|  |  | Interactive operating guide | Interactive guide for operation and troubleshooting via help function |  |  |  |  |  |  |  |  |  |  |
| \% | Functions |  | Overcurrent cutoff (during acceleration, deceleration, constant speed), regenerative overvoltage cutoff, undervoltage, instantaneous power failure, overload cutoff (electronic thermal relay), ground fault overcurrent, output short circuit, overheating of main circuit, stall prevention, overload warning, fin overheating, fan error, option error, parameter error, PU connection error, No. of retries over, output open phase, CPU error, 24V DC power supply output short circuit, operation panel power supply short circuit, output of group error message via relay contact (230V AC / 0.3A; 30V DC / 0.3A). |  |  |  |  |  |  |  |  |  |  |
|  | Protective structure |  | IP 00 |  |  |  |  |  |  |  |  |  |  |
|  | Ambient temperature in operation |  | $-10^{\circ} \mathrm{C} \text { to }+50^{\circ} \mathrm{C} \text { (non freezing) }$ <br> (For selection of the overload capacity of $120 \%$ the max. temperature is $40^{\circ} \mathrm{C}$. |  |  |  |  |  |  |  |  |  |  |
|  | Storage temperature ${ }^{(5)}$ |  | $-20^{\circ} \mathrm{C}$ to $+65^{\circ} \mathrm{C}$ |  |  |  |  |  |  |  |  |  |  |
|  | Ambient humidity |  | Max. 90\% RH (non-condensing) |  |  |  |  |  |  |  |  |  |  |
|  | Ambience condition |  | For indoor use only, avoid environments containing corrosive gases, no oil mist, install in a dust-free location |  |  |  |  |  |  |  |  |  |  |
|  | Altitude |  | Max. 1000 m above $\mathrm{n} . \mathrm{N}$. |  |  |  |  |  |  |  |  |  |  |
|  | Vibration resistance |  | Max. 0.6 g |  |  |  |  |  |  |  |  |  |  |
|  | Cooling |  | Fan-cooling |  |  |  |  |  |  |  |  |  |  |
|  | Weight [kg] |  | 41 | 57 | 66 | 66 | 68 | 120 | 120 | 220 | 235 | 490 | 500 |

## NOTES

Special notes referring to the table:
(1) The applicable motor capacity refers to a motor voltage of 400 V .The overload capacity indicated in \% describes the ratio to the inverter's rated current according to the operation mode. For repeated duty, allow time for the inverter and motor to return to or below the temperatures under $100 \%$ load. The calculation of the pause times is made by using the effective current calculation method $\left(1^{2} \times \mathrm{t}\right)$. That means, that you have to know the working cycle.
(3)

The maximum output voltage cannot exceed the power supply voltage.
The maximum output voltage may be set as desired below the power supply voltage.
${ }^{(4)}$ The power supply capacity changes with the values of the power supply side inverter impedances (including those of the input reactor and cables).
${ }^{(5)}$ Temperature applicable for a short period in transit, etc.
(6) At $120 \%$ rating a maximum ambient temperature of $40^{\circ} \mathrm{C}$ is allowed.

## 3 Appearance and Structure

### 3.1 Description of the Case

Depending on the capacity class the frequency inverter is delivered in second different structural shapes of the case. The following drawings show a structured view of the single case components.

Frequency inverter FR-F 540L EC with front cover


Frequency inverter FR-F 540L EC without front cover


## 4 Wiring

### 4.1 Overview

## CAUTION: <br> The terminals PC-SD of the 24V DC power supply must not be shorted. Otherwise the inverter will be damaged.


(1) The JOG terminal is connected internally for the frequency inverters FR-A 540L-G375 k and G450 k and cannot be used by the customer.
(2) The designations and wiring of the intermediate circuit connections varies depending on the output of the frequency inverter model (see also section 4.2.1).

The connection of the enclosed DC choke coil is described on page 14.

### 4.2 Wiring of the Main Circuit

## DANGER:

The frequency inverter must always be powered off completely before performing any wiring work. To ensure that no residual charge is present check that both the POWER and CHARGE LEDs are off before starting work!

## CAUTION:

Power must not be applied to the output terminals (U, V, W) of the inverter. Otherwise the inverter will be damaged.
The inverter must be grounded using the dedicated ground terminal.

### 4.2.1 Mains, Motor and Ground Terminal Connections

The terminal blocks for connection of the frequency inverter can be accessed by removing the terminal block cover. The mains power supply is connected to terminals L1, L2 and L3. Required power supply: $380-480 \mathrm{~V},-15 \% /+10 \% ; 50-60 \mathrm{~Hz} \pm 5 \%$.

Connect the motor cables to terminals U, V and W. The illustration below shows the correct assignments for the power connections. Please see the main frequency inverter manual for details on the required cable dimensions for your model.

NOTE $\quad \mid$ The inverter must be grounded using the dedicated ground terminal.


NOTE $\quad \mid$ It is recommended to use a shielded motor cable in order to reduce cable radiation.


## NOTE

The maximum wiring length of the motor cable is 500 m .
The following table shows the terminal assignment of main circuit terminals.

|  | Terminal | Terminal name | Description |
| :---: | :---: | :---: | :---: |
|  | L1, L2, L3 | Mains supply connection | Mains power supply of the inverter ( $380-480 \mathrm{~V}$ AC, $50 / 60 \mathrm{~Hz}$ ) |
|  | P/+, N/- | External brake unit connection | An external brake unit can be connected to the terminals $\mathrm{P} /+$ and $\mathrm{N} /-$. |
|  | $\begin{aligned} & \text { P1, P/+ } \\ & \text { (P0, P1) } \end{aligned}$ | DC choke coil connection | An optional choke coil can be connected to the terminals P1 and P/+ (up to 375k) or between P0 and P1 (450k to 530k) respectively. <br> The supplied choke coil has to be installed to the mentioned terminals. |
|  | U, V, W | Motor connection | Voltage output of the inverter (3 ~ 0V- power supply voltage, $0.5-120 \mathrm{~Hz}$ ) |
|  | L11, L21 | Control circuit mains supply connection | Mains power supply input for a separate supply of the control circuit (refer to paragraph 4.2.2). |
|  | $\stackrel{1}{-}$ | PE | Protective earth connection of inverter |

## CAUTION:

Switching the unit off and on repeatedly with the mains power supply at short intervals can damage the switch-on current limiter. Because of this the unit should always be started and stopped with the control unit or via the STF/STR and STOP control signals.

### 4.2.2 Separate Power Supply for the Control Circuit

In an alarm condition the frequency inverter's integrated alarm relay only remains active as long as there is a mains power supply on terminals L1, L2 and L3. If you want the alarm signal to remain active after the frequency inverter has been switched off a separate power supply for the control circuit is required, which should be connected as shown in the circuit diagram below. Remove the shorting jumpers from the terminal block and connect the $380-480 \mathrm{~V}$ AC, $50 / 60 \mathrm{~Hz}$ mains power supply to terminals L11 and L21. The control circuit power consumption on L11/L21 is 120VA. We recommend using a fuse with a rating of at least 5A to protect the circuit.


## CAUTION:

When using a separate power supply, the jumpers must be removed and the terminals L11 and L21 of the terminal block must be connected.

Remove the jumpers as follows:
(1) Loosen the upper screws (1) and then the lower screws (2)
(2) Pull out and remove the jumper (3.
(3) Connect the seperate power supply for control circuits to the upper terminals 4 L11 and L21.


## CAUTION:

The seperate power supply must not be connected to the lower terminals. Otherwise the inverter may be damaged.

### 4.3 Wiring of the Control Circuit

The following picture shows the arrangement of the terminal for the control circuit of the inverter.


|  | Terminal | Terminal name | Description |
| :---: | :---: | :---: | :---: |
|  | STF | Forward rotation start | The motor rotates forward, if a signal is applied to terminal STF. |
|  | STR | Reverse rotation start | The motor rotates reverse, if a signal is applied to terminal STR. |
|  | STOP | Start self-retaining selection | The start signals are self-retaining, if a signal is applied to terminal STOP. |
|  | RH, RM, RL | Multi-speed selection | Preset of 15 different output frequencies |
|  | JOG | JOG mode selection | The JOG mode is selected, if a signal is applied to terminal JOG (factory setting). <br> The start signals STF and STR determine the rotation direction. <br> The inverters FR-F 540L-450 k and 530 k are not equipped with a JOG terminal. |
|  | RT | Second parameter settings | A second set of parameter settings is selected, if a signal is applied to terminal RT. |
|  | MRS | Output stop | The inverter lock stops the output frequency without regard to the delay time. |
|  | RES | RESET input | An activated protective circuit is reset, if a signal is applied to the terminal RES ( $\mathrm{t}>0.1 \mathrm{~s}$ ). |
|  | AU | Current input selection | Only if the AU signal is ON, the inverter can be operated with the $0 / 4-20 \mathrm{~mA}$ frequency setting signal. |
|  | CS | Automatic restart after power failure selection | The inverter restarts automatically after a power failure, if a signal is applied to the terminal CS. Note that this operation requires restart parameters to be set. When the inverter is shipped from the factory, it is set to disallow restart. |
| $\begin{aligned} & \text { ᄃ } \\ & \stackrel{\theta}{\varepsilon} \\ & 0 \\ & 0 \end{aligned}$ | SD | Common sink for contact input/reference potential | A determined control function is activated, if the corresponding terminal is connected to the terminal SD (sink logic). The SD terminal is isolated from the digital circuits via optocouplers. Reference potential for the pulse output FM. The terminal is isolated from the reference potential of the control circuit. Common reference potential for 24 V DC/0.1A output (PC terminal). |
|  | PC | 24 V DC output and control input common if source logic type is activated | 24-V-DC-/0.1-A-Output <br> With negative logic and control via open collector transistors (e.g. a PLC) the positive pole of an external power source must be connected to the PC terminal. With positive logic the PC terminal is used as a common reference for the control inputs. This means that when positive logic is selected (default setting of the EC units) the corresponding control function is activated by connecting its terminal to the PC terminal. |


|  | Terminal | Terminal name | Description |
| :---: | :---: | :---: | :---: |
| Setting value specification | 10 E (output voltage 10V DC) | Voltage output for potentiometer | Output voltage 10V DC <br> Max. output current 10 mA . <br> Recommended potentiometer: $1 \mathrm{k} \Omega$, 2 W linear, multiturn potentiometer |
|  | 10 (output voltage 5V DC) |  | Output voltage 5V DC <br> Max. output current 10 mA . <br> Recommended potentiometer: $1 \mathrm{k} \Omega$, 2 W linear, multiturn potentiometer |
|  | 2 | Input for frequency setting value signal | The voltage setting value $0-5(10) \mathrm{V}$ is applied to this terminal. The voltage range is preset to $0-5 \mathrm{~V}$ (Parameter 73). The input resistance is $10 \mathrm{k} \Omega$. |
|  | 5 | Reference point for frequency setting value signal | Terminal 5 is the reference point for all analog setting values and for the analog output signal AM. The terminal is not isolated from the reference potential of the control circuit and must not be earthed. |
|  | 1 | Auxiliary input for frequency setting value signal $0- \pm 5(10) V D C$ | An additional voltage setting value signal of $0- \pm 5$ (10)V DC can be applied to terminal 1. The voltage range is preset to $0- \pm 10 \mathrm{~V}$ DC. The input resistance is $10 \mathrm{k} \Omega$. |
|  | 4 | Input for current setting value signal 0/4-20mA DC | The current setting value signal ( $0 / 4-20 \mathrm{~mA} \mathrm{DC}$ ) is applied to this terminal. The input resistance is $250 \Omega$, the max current is 30 mA . |
|  | A, B, C | Potential free alarm output | The alarm is output via relay contacts. The block diagram shows the normal operation and voltage free status. If the protective function is activated, the relay picks up. <br> The maximum contact load is $230 \mathrm{~V} / 0.3 \mathrm{~A} \mathrm{AC}$ or 30V / 0.3 ADC. |
|  | RUN | Signal output for motor operation (Open Collector) | The output is switched low, if the inverter output frequency is equal to or higher than the starting frequency. The output is switched high, if no frequency is output or the DC brake is in operation. |
|  | SU | Signal output for frequency setting value / current value comparison (Open Collector) | The SU output supports a monitoring of frequency setting value and frequency current value. The output is switched low, once the frequency current value (output frequency of the inverter) approaches the frequency setting value (determined by the setting value signal) within a preset range of tolerance (parameter 41). |
|  | IPF | Signal output for instantaneous power failure (Open Collector) | The output is switched low for a temporary power failure within a range of $15 \mathrm{~ms} \leq \mathrm{t}_{\text {IPF }} \leq 100 \mathrm{~ms}$ or for undervoltage. |
|  | OL | Signal output for overload alarm (Open Collector) | The OL is switched low, if the output current of the inverter exceeds the current limit preset in parameter 22 and the stall prevention is activated. If the output current of the inverter falls below the current limit preset in parameter 22, the signal at the OL output is switched high. |


|  | Terminal | Terminal name | Description |
| :---: | :---: | :---: | :---: |
|  | FU | Signal output for monitoring output frequency (Open Collector) | The output is switched low once the output frequency exceeds a value preset in parameter 42 (or 43). Otherwise the FU output is switched high. |
|  | SE | Reference potential for signal outputs | Reference potential for the signals RUN, SU, OL, IPF, and FU. This terminal is isolated from the reference potential of the control circuit SD. |
|  | FM | Pulse output | One of 16 monitoring functions can be selected, e.g. external frequency output (parameter 54; parameter 158). FM and AM output can be used simultaneously. <br> The functions are determined by parameters. Either a moving coil gauge (measuring range: 1 mA ) or a pulse counter with an initial setting of 1440 pulses $/ \mathrm{s}$ at 50 Hz output frequency. |
|  | AM | Analog output | One of 16 monitoring functions can be selected, e.g. external frequency output (parameter 54; parameter 158). FM and AM output can be used simultaneously. <br> The functions are determined by parameters. A DC voltmeter can be connected. The max. output voltage is 10 V , the max. current is 1 mA . |
|  | - | Connection of control panel (RS485) | Communications via RS485 <br> I/O-Standard: RS485, Multi-Drop operation, max. <br> 19200Baud, Overall length max. 500m |

## CAUTION:

Terminals 10/10E and 5 must not be connected to each other. Otherwise the internal voltage output for the connection of the potentiometer will be damaged.

The control signal level can be adjusted with the jumper on the underside of the removable control terminal block (unscrew the two retaining screws to remove). At the factory the jumper on the EC units is set to the "Source" position (positive logic, 24V DC corresponds to logical 1). If you want to use negative logic (0V corresponds to logical 1) you must move the jumper to the "Sink" position. Use tweezers or thin-nosed pliers to move the jumper.

The control terminals RL/RM/RH/RT/AU/JOG/CS (input terminals) and RUN/SU/IPF/OL/ FU/A, B, C (output terminals) can be assigned to other functions or signals with the help of the control unit (FR-DU04 or FR-PU04), the PC software or a field bus system. Please see the frequency inverter manual for details on the procedure for this.

Please note the following important points for proper frequency inverter control performance:

- The following conditions must be fulfilled for the frequency inverter to output a rotating field correctly:
- The inverter lock must be deactivated (see below).
- You must input both a direction of rotation signal and a frequency setpoint value to the inverter.
- If the frequency inverter does not work properly even though the wiring of the control terminals block appears to be correct please check the following points:
- Is the frequency inverter reporting an error condition (red alarm LED)?
- Is the correct operating mode selected (EXT mode for control via the terminal block, PU mode for control via the control unit)?
- Is the inverter lock (terminal MRS) deactivated and is the inverter receiving a rotation start signal (terminal STF or STR)?
- Is the inverter receiving a valid frequency setpoint value > the start frequency (voltage signal on terminal 2, current signal on terminal 4, preset frequency digital inputs)?
- Are the control terminals you are using programmed correctly?


## 5 Parameters

### 5.1 Overview and Setting Ranges

Parameter 160 is factory set to " 9999 ". That means that only the half-tone screened parameters in the following table are accessible. Set parameter 160 to "0" to access other or all parameters.

| Function | Parameter | Meaning | Setting range | Default setting |
| :---: | :---: | :---: | :---: | :---: |
| Basic functions | 0 | Torque boost (manual) | 0-30\% | 1\% |
|  | 1 | Maximum frequency | $0-120 \mathrm{~Hz}$ | 60 Hz |
|  | 2 | Minimum frequency | $0-120 \mathrm{~Hz}$ | 0 Hz |
|  | 3 | Base frequency | 0-120Hz | 50 Hz |
|  | 4 | Multi-speed setting (high speed) ${ }^{2}$ | $0-120 \mathrm{~Hz}$ | 60 Hz |
|  | 5 | Multi-speed setting (middle speed) ${ }^{(2)}$ | $0-120 \mathrm{~Hz}$ | 30 Hz |
|  | 6 | Multi-speed setting (low speed) ${ }^{(2)}$ | $0-120 \mathrm{~Hz}$ | 10Hz |
|  | 7 | Acceleration time | 0-360s / 0-3600s | 15s |
|  | 8 | Deceleration time | 0-360s / 0-3600s | 30 |
|  | 9 | Electronic thermal overload relay | 0-3600A | Rated current |
| Standard operation functions | 10 | DC injection brake operation frequency | 0-120Hz / 9999 | 3 Hz |
|  | 11 | DC injection brake operation time | 0-10s / 8888 | 0.5s |
|  | 12 | DC injection brake voltage | 0-30\% | 1\% |
|  | 13 | Starting frequency | $0-60 \mathrm{~Hz}$ | 0.5 Hz |
|  | 14 | Load pattern selection | $0 / 1$ | 1 |
|  | 15 | JOG frequency | $0-120 \mathrm{~Hz}$ | 5 Hz |
|  | 16 | JOG acceleration / deceleration time | 0-360s / 0-3600s | 0.5 s |
|  | 17 | MRS input selection | $0 / 2$ | 0 |
|  | 19 | Base frequency voltage | 0-1000V/8888/9999 | 8888 |
|  | 20 | Acceleration / deceleration reference frequency | $1-120 \mathrm{~Hz}$ | 50 Hz |
|  | 21 | Acceleration / deceleration time increments | $0 / 1$ | 0 |
|  | 22 | Stall prevention operation level ${ }^{(2)}$ | 0-150\% / 9999 | 120\% |
|  | 23 | Stall prevention operation at double speed | 0-200\% / 9999 | 9999 |
|  | 24 | Multi-speed setting (speed 4) ${ }^{(2)}$ | 0-120Hz / 9999 | 9999 |
|  | 25 | Multi-speed setting (speed 5) ${ }^{(2)}$ | 0-120Hz / 9999 | 9999 |
|  | 26 | Multi-speed setting (speed 6) ${ }^{(2)}$ | 0-120Hz / 9999 | 9999 |
|  | 27 | Multi-speed setting (speed 7) ${ }^{(2)}$ | 0-120Hz / 9999 | 9999 |
|  | 28 | Multi-speed input compensation | $0 / 1$ | 0 |
|  | 29 | Acceleration / deceleration pattern | $0 / 1 / 2 / 3$ | 0 |
|  | 30 | Regenerative function selection | $0 / 1 / 2$ | 0 |


| Function | Parameter | Meaning | Setting range | Default setting |
| :---: | :---: | :---: | :---: | :---: |
| Standard operation functions | 31 | Frequency jump 1A | 0-120Hz / 9999 | 9999 |
|  | 32 | Frequency jump 1B | 0-120Hz / 9999 | 9999 |
|  | 33 | Frequency jump 2A | 0-120Hz / 9999 | 9999 |
|  | 34 | Frequency jump 2B | 0-120Hz / 9999 | 9999 |
|  | 35 | Frequency jump 3A | 0-120Hz / 9999 | 9999 |
|  | 36 | Frequency jump 3B | 0-120Hz / 9999 | 9999 |
|  | 37 | Speed display | 0 / 1-9998 | 0 |
|  | 38 | Automatic torque boost (motor capacity) | 0-200\% | 0 |
|  | 39 | Automatic torque boost operation starting current | 0-3600A | 0 |
| Output terminal functions | 41 | Up-to-frequency sensitivity | 0-100\% | 10\% |
|  | 42 | Output frequency detection (FU-Output) | $0-120 \mathrm{~Hz}$ | 6 Hz |
|  | 43 | Output frequency detection for reverse rotation | 0-120Hz / 9999 | 9999 |
| Second functions | 44 | Second acceleration/deceleration time | 0-360s / 0-3600s | 5 s |
|  | 45 | Second deceleration time | $\begin{gathered} \hline 0-360 s / 0-3600 \mathrm{~s} / \\ 9999 \\ \hline \end{gathered}$ | 9999 |
|  | 46 | Second torque boost | 0-30\% / 9999 | 9999 |
|  | 47 | Second V/F (base frequency) | 0-120Hz / 9999 | 9999 |
|  | 48 | Second stall prevention operation current | 0-150\% | 120\% |
|  | 49 | Second stall prevention operation frequency | 0-120Hz / 9999 | 0 |
|  | 50 | Second output frequency detection | $0-120 \mathrm{~Hz}$ | 30 Hz |
| Display functions | 52 | DU/PU main display data selection ${ }^{(2)}$ | $\begin{array}{\|c\|} \hline 0 / 5 / 6 / 8 / \\ 10-14 / 17 / 20 / 23 / \\ 24 / 25 / 100 \\ \hline \end{array}$ | 0 |
|  | 53 | PU level display data selection ${ }^{(2)}$ | $\begin{gathered} 0-3 / 5 / 6 / 8 / \\ 10-14 / 17 \end{gathered}$ | 1 |
|  | 54 | FM terminal function selection ${ }^{(2)}$ | $\begin{aligned} & 1-3 / 5 / 6 / 8 / \\ & 10-14 / 17 / 21 \end{aligned}$ | 1 |
|  | 55 | Frequency monitoring reference ${ }^{(2)}$ | $0-120 \mathrm{~Hz}$ | 50 Hz |
|  | 56 | Current monitoring reference ${ }^{(2)}$ | 0-3600A | Rated current |
| Automatic restart functions | 57 | Restart coasting time | 0-30s / 9999 | 9999 |
|  | 58 | Restart cushion time | 0-60s | 1s |
| Additional function | 59 | Remote setting function selection | 0/1/2 | 0 |
| Operation selection functions | 60 | Intelligent mode selection | $0 / 3 / 4$ / 9 | 0 |
|  | 61 | Reference I for intelligent mode | 0-3600A / 9999 | 9999 |
|  | 62 | Reference I for intelligent mode (acceleration) | 0-150\% / 9999 | 9999 |
|  | 63 | Reference I for intelligent mode (deceleration) | 0-150\% / 9999 | 9999 |
|  | 65 | Retry selection | 0-5 | 0 |
|  | 66 | Stall prevention operation reduction starting frequency | $0-120 \mathrm{~Hz}$ | 50 Hz |
|  | 67 | Number of retries at alarm occurrence | 0-10 / 101-110 | 0 |
|  | 68 | Retry waiting time | 0-10s | 1 s |
|  | 69 | Retry count display erasure | 0 | 0 |
|  | 70 | Special regenerative brake duty | 0-100\% | 0\% |


| Function | Parameter | Meaning | Setting range | Default setting |
| :---: | :---: | :---: | :---: | :---: |
| Operation selection functions | 71 | Applied motor | 0/1/2 | 0 |
|  | 72 | PWM frequency selection ${ }^{(2)}$ | $0 / 1 / 2 / 17$ | 1 |
|  | 73 | 0-5V / 0-10V selection | 0-5 / 10-15 | 1 |
|  | 74 | Filter time constant | 0-8 | 1 |
|  | 75 | Reset selection / disconnected PU detection / PU stop selection | 0-3 / 14-17 | 14 |
|  | 76 | Alarm code output selection | 0/1/2 | 0 |
|  | 77 | Parameter write disable selection ${ }^{(2)}$ | 0/1/2 | 0 |
|  | 78 | Reverse rotation prevention selection | 0/1/2 | 0 |
|  | 79 | Operation mode selection | 0-4/6-8 | 0 |
| 5-point flexible V/f characteristics | 100 | V/f1 (first frequency) | 0-120Hz / 9999 | 9999 |
|  | 101 | V/f1 (first frequency voltage) | 0-1000V | 0 |
|  | 102 | $\mathrm{V} / \mathrm{f} 2$ (second frequency) | 0-120Hz / 9999 | 9999 |
|  | 103 | V/f2 (second frequency voltage) | 0-1000V | 0 |
|  | 104 | V/f3 (third frequency) | 0-120Hz / 9999 | 9999 |
|  | 105 | V/f3 (third frequency voltage) | 0-1000V | 0 |
|  | 106 | V/f4 (fourth frequency) | 0-120Hz / 9999 | 9999 |
|  | 107 | V/f4 (fourth frequency voltage) | 0-1000V | 0 |
|  | 108 | V/f5 (fifth frequency) | 0-120Hz / 9999 | 9999 |
|  | 109 | V/f5 (fifth frequency voltage) | 0-1000V | 0 |
| Communications functions | 117 | Station number | 0-31 | 0 |
|  | 118 | Communication speed | 48 / 96 / 192 | 192 |
|  | 119 | Stop bit length / data length | 0 / 1 Data length 8 10/11 Data length 7 | 1 |
|  | 120 | Parity check presence / absence | 0/1/2 | 2 |
|  | 121 | Number of communication retries | 0-10 / 9999 | 1 |
|  | 122 | Communication check time interval | 0-999.8s / 9999 | 9999 |
|  | 123 | Waiting time setting | 0-150ms / 9999 | 9999 |
|  | 124 | CR / LF presence / absence selection | 0/1/2 | 1 |
| PID- <br> Regelung | 128 | PID action selection | 10 / 11/20 / 21 | 10 |
|  | 129 | PID proportional band | 0.1-1000\% / 9999 | 100\% |
|  | 130 | PID integral time | 0.1-3600s / 9999 | 1 s |
|  | 131 | Upper limit | 0-100\% / 9999 | 9999 |
|  | 132 | Lower limit | 0-100\% / 9999 | 9999 |
|  | 133 | PID action set point for PU operation | 0-100\% | 0\% |
|  | 134 | PID differential time | 0.01-10.00s / 9999 | 9999 |
| Commercial power supplyinverter switch-over | 135 | Commercial power supply-inverter switch-over sequence output terminal selection | $0 / 1$ | 0 |
|  | 136 | MC switch-over interlock time | 0-100.0s | 1.0s |
|  | 137 | Start waiting time | 0-100.0s | 0.5 s |
|  | 138 | Commercial power supply-inverter switch-over selection at alarm occurrence | $0 / 1$ | 0 |
|  | 139 | Automatic inverter-commercial power supply switch-over frequency | 0-60Hz / 9999 | 9999 |


| Function | Parameter | Meaning | Setting range | Default setting |
| :---: | :---: | :---: | :---: | :---: |
| Backlash | 140 | Backlash acceleration stopping frequency ${ }^{(1)}$ | 0-120Hz | 1.00 Hz |
|  | 141 | Backlash acceleration stopping time ${ }^{(1)}$ | 0-360s | 0.5 s |
|  | 142 | Backlash deceleration stopping frequency ${ }^{(1)}$ | $0-120 \mathrm{~Hz}$ | 1.00 Hz |
|  | 143 | Backlash deceleration stopping time ${ }^{(1)}$ | 0-360s | 0.5 s |
| Display | 144 | Speed setting switchover | $\begin{gathered} 0 / 2 / 4 / 6 / 8 / 10 / \\ 102 / 104 / 106 / \\ 108 / 110 \end{gathered}$ | 4 |
|  | 145 | PU language selection | 0-7 | 1 |
| Additional functions | 148 | Stall prevention level at OV input | 0-150\% | 120\% |
|  | 149 | Stall prevention level at 10 V input | 0-150\% | 150\% |
| Current detection | 152 | Zero current detection level | 0-200.0\% | 5\% |
|  | 153 | Zero current detection period | 0-1s | 0.5 s |
| Help functions | 154 | Voltage reduction selection during stall prevention operation | $0 / 1$ | 1 |
|  | 155 | RT activated condition | $0 / 10$ | 0 |
|  | 156 | Stall prevention operation selection | 0-31/100 / 101 | 0 |
|  | 157 | OL signal waiting time | 0-25s | 0 |
|  | 158 | AM terminal function selection | $\begin{aligned} & 1-3 / 5 / 6 / 8 / \\ & 10-14 / 17 / 21 \end{aligned}$ | 1 |
| Additional functions | 160 | User group read selection ${ }^{(2)}$ | 0 / 1/10 / 11/9999 | 9999 |
| Automatic restart after instantaneous power failure | 162 | Automatic restart after instantaneous failure selection | $0 / 1$ | 0 |
|  | 163 | First cushion time for restart | 0-20s | Os |
|  | 164 | First cushion voltage for restart | 0-100\% | 0\% |
|  | 165 | Restart stall prevention operation level | 0-150\% | 120\% |
| Additional functions | 168 | Parameter set by manufacturer: Do not set! |  |  |
|  | 169 |  |  |  |
| Initial monitor | 170 | Watt-hour meter clear | 0 | 0 |
|  | 171 | Actual operation hour meter clear | 0 | 0 |
| User group | 173 | User group 1 registration | 0-999 | 0 |
|  | 174 | User group 1 deletion | 0-999 / 9999 | 0 |
|  | 175 | User group 2 registration | 0-999 | 0 |
|  | 176 | User group 2 deletion | 0-999 / 9999 | 0 |
| Terminal function selection | 180 | RL terminal function selection | $\begin{gathered} 0-7 / 10-14 / \\ 16 / 9999 \end{gathered}$ | 0 |
|  | 181 | RM terminal function selection |  | 1 |
|  | 182 | RH terminal function selection |  | 2 |
|  | 183 | RT terminal function selection |  | 3 |
|  | 184 | AU terminal function selection |  | 4 |
|  | 185 | JOG terminal function selection ${ }^{(3)}$ |  | 5 |
|  | 186 | CS terminal function selection |  | 6 |
|  | 190 | RUN terminal function selection | $\begin{gathered} 0-5 / 8 / 10 / 11 / \\ 13-19 / 26 / \\ 98-105 / 108 / 110 / \\ 111 / 113-116 / \\ 126 / 198 / \\ 199 / 9999 \end{gathered}$ | 0 |
|  | 191 | SU terminal function selection |  | 1 |
|  | 192 | IPF terminal function selection |  | 2 |
|  | 193 | OL terminal function selection |  | 3 |
|  | 194 | FU terminal function selection |  | 4 |
|  | 195 | ABC terminal function selection |  | 99 |
| Additional function | 199 | User initial value setting | 0-999 / 9999 | 0 |


| Function | Parameter | Meaning | Setting range | Default setting |
| :---: | :---: | :---: | :---: | :---: |
| Auxiliary functions | 240 | Soft-PWM setting ${ }^{(2)}$ | $0 / 1$ | 1 |
|  | 244 | Cooling fan operation selection | $0 / 1$ | 0 |
| Supplementary functions | 251 | Output phase failure protection selection | $0 / 1$ | 1 |
|  | 252 | Override bias | 0-200\% | 50\% |
|  | 253 | Override gain | 0-200\% | 150\% |
| Parameter für Optionen | 300 | BCD code input bias | $0-400 \mathrm{~Hz}$ | 0 Hz |
|  | 301 | BCD code input gain | 0-400Hz / 9999 | 50 Hz |
|  | 302 | Binary input bias | $0-400 \mathrm{~Hz}$ | OHz |
|  | 303 | Binary input gain | 0-400Hz / 9999 | 50 Hz |
|  | 304 | Selection of digital input type/analog compensation input enable/disable | 0 / 1 / 2 / 3 / 9999 | 9999 |
|  | 305 | Data read timing signal on-off selection | $0 / 1$ | 0 |
|  | 306 | Analog output signal selection | 1-24 | 2 |
|  | 307 | Setting for zero analog output | 0-100\% | 0\% |
|  | 308 | Setting for maximum analog output | 0-100\% | 100\% |
|  | 309 | Voltage / current selection for analog output signal | $0 / 1 / 10 / 11$ | 0 |
|  | 310 | Analog meter voltage output selection | 1-24 | 2 |
|  | 311 | Setting for zero analog meter voltage output | 0-100\% | 0\% |
|  | 312 | Setting for maximum analog meter voltage output | 0-100\% | 100\% |
|  | 313 | Y0 output selection | 0-199 / 9999 | 9999 |
|  | 314 | Y1 output selection | 0-199 / 9999 | 9999 |
|  | 315 | Y2 output selection | 0-199 / 9999 | 9999 |
|  | 316 | Y3 output selection | 0-199 / 9999 | 9999 |
|  | 317 | Y4 output selection | 0-199 / 9999 | 9999 |
|  | 318 | Y5 output selection | 0-199 / 9999 | 9999 |
|  | 319 | Y6 output selection | 0-199 / 9999 | 9999 |
|  | 320 | RA1 output selection | 0-99 / 9999 | 0 |
|  | 321 | RA2 output selection | 0-99 / 9999 | 1 |
|  | 322 | RA3 output selection | 0-99 / 9999 | 2 |
|  | 330 | RA output selection | $\begin{gathered} 0-20 / 25-31 / 98 / \\ 99 / 9999 \end{gathered}$ | 9999 |
|  | 331 | Station number | 0-31 | 0 |
|  | 332 | Communication speed | $\begin{gathered} 3 / 6 / 12 / 24 / 48 / \\ 96 / 192 \end{gathered}$ | 96 |
|  | 333 | Stop bit length/Data length | $0 / 1 / 10 / 11$ | 1 |
|  | 334 | Parity check presence / absence | 0/1/2 | 2 |
|  | 335 | Number of communication retries | 0-10 / 9999 | 1 |
|  | 336 | Communication check time interval | 0-999.8s / 9999 | 0 |
|  | 337 | Waiting time setting | 0-150ms / 9999 | 9999 |
| Communication | 338 | Operation command write | $0 / 1$ | 0 |
|  | 339 | Speed command write | $0 / 1$ | 0 |
|  | 340 | Link start mode selection | 0/1/2 | 0 |
|  | 341 | CR, LF presence / absence selection | 0/1/2 | 1 |
| Supplementary function | 342 | E2PROM write yes/no | $0 / 1$ | 0 |


| Function | Parameter | Meaning | Setting range | Default setting |
| :---: | :---: | :---: | :---: | :---: |
| Advanced PID control | 500 | Auxiliary motor operation selection | 0/1/2/3 | 0 |
|  | 501 | Motor switch-over selection | 0/1/2 | 0 |
|  | 502 | MC switching interlock time | 0-100s | 1s |
|  | 503 | Start waiting time | 0-100s | 1 s |
|  | 504 | Auxiliary motor connection-time deceleration time | 0-3600s | 1 s |
|  | 505 | Auxiliary motor disconnection-time acceleration time | 0-3600s / 9999 | 1s |
|  | 506 | Output stop detection time | 0-3600s / 9999 | 9999 |
|  | 507 | Output stop detection level | 0-120Hz | 0 Hz |
|  | 508 | Output stop cancel process value level | 0-100\% | 100\% |
|  | 509 | Auxiliary motor 1 starting frequency | $0-120 \mathrm{~Hz}$ | 50 Hz |
|  | 510 | Auxiliary motor 2 starting frequency | $0-120 \mathrm{~Hz}$ | 50 Hz |
|  | 511 | Auxiliary motor 3 starting frequency | $0-120 \mathrm{~Hz}$ | 50 Hz |
|  | 512 | Auxiliary motor 1 stopping frequency | $0-120 \mathrm{~Hz}$ | OHz |
|  | 513 | Auxiliary motor 2 stopping frequency | $0-120 \mathrm{~Hz}$ | 0 Hz |
|  | 514 | Auxiliary motor 3 stopping frequency | $0-120 \mathrm{~Hz}$ | OHz |
|  | 515 | Auxiliary motor start delay frequency | 0-3600s | 5 s |
|  | 516 | Auxiliary motor stop delay frequency | 0-3600s | 5 s |
| Suplementary functions | 570 | CT / VT selection (only Version "Type 02") | $1 / 2$ | 1 |
|  | 571 | Start holding time | $\begin{gathered} 0-10 s ~ / ~ \\ 9999 \end{gathered}$ | 9999 |
| Calibration functions | 900 | FM terminal calibration ${ }^{(2)}$ | Calibration range | - |
|  | 901 | AM terminal calibration ${ }^{(2)}$ | Calibration range | - |
|  | 902 | Frequency setting voltage bias | $0-60 \mathrm{~Hz} /[0-10 \mathrm{~V}$ ] | OHz / [0V] |
|  | 903 | Frequency setting voltage gain | $1-120 \mathrm{~Hz} /[0-10 \mathrm{~V}]$ | $50 \mathrm{~Hz} /[5 \mathrm{~V}]$ |
|  | 904 | Frequency setting current bias | $0-60 \mathrm{~Hz} /[0-20 \mathrm{~mA}]$ | $0 \mathrm{~Hz} /[4 \mathrm{~mA}]$ |
|  | 905 | Frequency setting current gain | $1-120 \mathrm{~Hz} /[0-20 \mathrm{~mA}]$ | $50 \mathrm{~Hz} /[20 \mathrm{~mA}]$ |
| Additional functions | 990 | Buzzer control | $0 / 1$ | 1 |
|  | 991 | LCD contrast | 0-63 | 53 |

Remarks on the table:
(1) Can only be accessed, if parameter 23 is set to the value 3 .
(2) These parameters allow their settings to be changed during operation if 0 (factory setting) has been set in Pr. 77 (Note that the Pr. 72 and Pr. 240 settings cannot be changed during external operation.). Wether a parameter can be changed during operation depends also on the setting of parameter 160.
(3) This terminal is connected internally for the frequency inverters FR-F 540L-450 k and 530 k and cannot be used by the customer.

## 6 Protective Functions

### 6.1 Error Messages and Remedies



| Error Message |  | Meaning | Description | Remedy |
| :---: | :---: | :---: | :---: | :---: |
| Control Panel FR-PU04 | Control Panel FR-DU04 |  |  |  |
| $\begin{aligned} & \text { Inct: } \\ & \text { Luse } \end{aligned}$ | E. $\|F\| F$ | Instantaneous power failure protection | The output of the inverter is sus-pended and the alarm message returned, if the power supply fails for more than 15 ms . If the power supply fails for more than 100 ms , the inverter shuts down completely. In this case after restoring the power supply the inverter is in the power ON state. If the power failure stays below 15 ms , the operation is proceeded normally. | Check the power supply. |
| Under: <br> yoltege | E.LILT | Undervoltage | The input voltage of the inverter has fallen below the minimum value. The protective function is activated, if the input voltage falls below the minimum value. | An undervoltage can occur, if the capacity of the mains transformer is not sufficient or if a high capacity motor is turned ON connected to the same mains supply circuit. |
| HSink DTEmF | EF 11 | Overheating of heat sink | In case of an overheating of the heat sink the temperature sensor responds and the inverter is stopped. | Check ambient temperature. |
| Ground Feult | EFIF | Ground failure | An overcurrent occured due to a ground failure upon the inverter output (load). | Check load connections (motor circuit). |
| OH Fsult. | E.IH-15 | Activation of an external motor protection relay (thermal contact) | An external motor protective switch was activated. <br> If an external motor protective switch for thermal monitoring is used, this switch can activate the protective function of the inverter. | Check motor load and drive. |
| $S_{5}^{t 11}$ | ETIL 5 | Stall prevention overload | A long lasting excess of the current limit (OL display) shuts down the inverter. | Reduce the load. Check the preset values for the current limit (parameter 22 ) and the stall prevention selection (parameter 156). |
| Fetiph | E.EIF | Error in an optional unit | A dedicated inboard option does not operate properly. The protective function is activated, if an internal option is improperly installed or connected. | Check connections and connectors of the optional unit. |
|  | $\begin{array}{ccc} \text { EIF } & 1 \\ \text { to } \\ \text { E.IF } \\ \text { El } \end{array}$ | Error in an optional unit | The protective function is activated for a fault (e.g. transmission error) of an internal optional unit. | Check the function settings of the optional unit. |
| Corrupt Hemt: | EFE | Memory error | Error on access of the data memory of the inverter | Please contact your nearest MITSUBISHI ELECTRIC representative if the error occurs repeatedly. |
| Fu Legue out. | EFUE | Control panel connection error | A connection error between inverter and control panel occurred during operation. <br> This alarm is only returned, if parameter 75 is set to " 2 ", " 3 ", " 16 ", or "17". | Check the connection of control panel. |
| Retres Ho. Duer | E.EF | Automatic restart retry exceeded | After activation of a protective function the inverter failed to be restarted automatically within the number of retries specified in parameter 67. | Remedy the actual cause of the originary protective function. |
| $\mathrm{CPU}$ | $E F F \mid l$ | CPU Fault | Scan time of CPU was exceeded. | Contact the customer service if the error occurs again. |


| Error Message |  | Meaning | Description | Remedy |
| :---: | :---: | :---: | :---: | :---: |
| Control Panel FR－PU04 | $\begin{array}{\|c\|} \hline \text { Control } \\ \text { Panel } \\ \text { FR-DU04 } \\ \hline \end{array}$ |  |  |  |
| Error E | $E$ E | CPU Fault | Scan time of CPU was exceeded． | Contact the customer service if the error occurs again． |
| Error ${ }^{\text {P }}$ | E．$\quad 1$ |  |  |  |
| － | E．r | Error | CPU error | Please contact your nearest MITSUBISHI ELECTRIC repre－ sentative if the error occurs re－ peatedly． |
| － | ELF | Open output phase protection | One of the phases $(\mathrm{U}, \mathrm{V}, \mathrm{W})$ is not connected． | Check the connections． |
| － | E．FEバイ | 24V DC power output short circuit | The 24V DC output at the PC ter－ minal is short circuited． | Eliminate short circuit． |
| － | EFIE | Short circuit in the control panel | The power supply of the control unit is short circuited． | Eliminate short circuit．Check the control panel and the connecting cable． |
| － | FIE | Inverter was stopped via con－ trol panel | STOP key on the control panel was pressed during external op－ erating mode． | Check the parameter 75 |
| OL | III | Overcurrent dur－ ing acceleration | If a current of more than $120 \%{ }^{(2)}$ of the rated inverter current flows in the motor，this function stops the increase of the frequency until the overload current reduces to prevent the inverter from resulting in overcurrent shut－off．When the overload current has reduced be－ low $120 \%$ ，this function increases the frequency again． | Change the acceleration／decel－ eration time．Increase the stall prevention operation level via Pr．22．Disable the stall preven－ tion via Pr． 156. |
|  |  | Overcurrent dur－ ing constant speed | If a current of more than $120 \%{ }^{(2)}$ of the rated inverter current flows in the motor，this function lowers the frequency until the overload current reduces to prevent the in－ verter from resulting in overcurrent shut－off．When the overload current has reduced below $120 \%$ ，this function in－ creases the frequency up to the set value． |  |
|  |  | Overcurrent dur－ ing deceleration | If a current of more than $120 \%{ }^{(2)}$ of the rated inverter current flows in the motor，this function stops the decrease of the frequency un－ til the overload current reduces to prevent the inverter from resulting in overcurrent shut－off．When the overload current has reduced be－ low $120 \%$ ，this function de－ creases the frequency again． |  |
| ¢L | －12 | Overvoltage dur－ ing deceleration | If the regenerative energy of the motor exceeds the brake capac－ ity of the inverter，this function stops the decrease of the fre－ quency to prevent overvoltage shut－off．When the regenerative energy has reduced，decelera－ tion resumes．As soon as the re－ generative energy has reduced， deceleration resumes． | Increase the deceleration time using Pr． 8 ＂deceleration time＂． |


| Error Message |  | Meaning | Description | Remedy |
| :---: | :---: | :---: | :---: | :---: |
| Control Panel FR-PU04 | $\begin{aligned} & \text { Control } \\ & \text { Panel } \\ & \text { FR-DU04 } \end{aligned}$ |  |  |  |
| - | Err | Error | This alarm appears if: <br> - the RES signal is on <br> - you attempted to set any parameter value in the external operation mode <br> - you attempted to change the operation mode during operation <br> - you attempted to set any parameter value outside its setting range | Perform operation correctly. |
| $E .15$ | E. $1_{1}$ | Main circuit failure | The heat sink of brake unit is overheated | Reduce the load moment or brake frequency; clean the heat sink; replace the cooling fan |
|  |  |  | DC fuse is blown | Eliminate the short-circuit and replace the fuse |
|  |  |  | The control board is overheated | Replace the cooling fan; check the ambient temperature |
|  |  |  | An overcurrent on the output has occured | Eliminate the short-circut or short to ground; replace the motor; increase the brake time; reduce the load fluctuations, increase the acceleration time; check the brake operation |
|  |  |  | Power supply for cooling fan fails | Eliminate the short-circuit; replace the power supply for cooling fan; replace the fuse |
|  |  |  | General overcurrent | Eliminate the short-circuit and replace the fuse; eliminate the short-circuit on output or short to ground; replace the motor and reduce the load |
|  |  |  | The heat sink is overheated | Clean or replace the heat sink; check the ambient temperature |
|  |  |  | A gate power supply failure has occured | Eliminate the short-circuit; replace the gate power supply |

(1) Refer to the instruction manual of the frequency inverter for a detailed description of the error message E. 15 .
${ }^{(2)}$ The stall prevention operation level (Pr. 22) is adjustable. It is factory-set to $120 \%$.

## 7 Dimensions

### 7.1 Inverters

### 7.1.1 Capacity Classes 75 k to 160 k



| Type | A | A1 | A2 | B | B1 | C | D |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FR-F 540L-75 k | 360 | 260 | 336 | 610 | 584 | 360 | 160 |
| FR-F 540L-90 k/110 k/132 k/160 k | 480 | 400 | 456 | 740 | 714 | 360 | 160 |

### 7.1.2 Capacity Classes 185 k to 375 k



| Type | A | A1 | A2 | B | B1 | C | D | E |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FR-F 540L-185 k/220 k | 498 | 200 | 474 | 1010 | 984 | 380 | 185 | 10 |
| FR-F 540L-280 k | 680 | 300 | 656 | 1010 | 984 | 380 | 185 | 10 |
| FR-F 540L-375 k | 790 | 315 | 766 | 1330 | 1300 | 440 | 196 | 12 |

### 7.1.3 Capacity Classes 450 k and 530 k



### 7.2 Converter Chokes

### 7.2.1 Capacity Classes 75 k to 280 k



Unit: mm

| Type | Dimensions |  |  |  |  |  |  |  |  |  |  | Weight [kg] |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | X | Y | Z | Z1 | B | H | G | S | S1 | S2 | $\varnothing$ |  |
| FR-F 540L-75 k | 140 | 170 | 320 | 230 | 120 | 295 | 25 | M6 | M6 | - | M10 | 14 |
| FR-F 540L-90 k | 150 | 175 | 337 | 265 | 130 | 310 | 25 | M6 | M6 | - | M12 | 18 |
| FR-F 540L-110 k | 150 | 180 | 337 | 255 | 130 | 310 | 25 | M6 | M6 | - | M12 | 19 |
| FR-F 540L-132 k | 175 | 185 | 400 | 300 | 150 | 365 | 32 | M8 | M6 | - | M12 | 22 |
| FR-F 540L 160 k | 175 | 190 | 400 | 315 | 150 | 365 | 32 | M8 | M6 | - | M12 | 22 |
| FR-F 540L-185 k | 175 | 225 | 400 | 285 | 150 | 365 | 32 | M8 | M6 | - | M12 | 29 |
| FR-F 540L-220 k | 190 | 225 | 438 | 305 | 165 | 400 | 38 | M8 | M8 | M8 | M12 | 36 |
| FR-F 540L-280 k | 210 | 235 | 495 | 350 | 185 | 450 | 44 | M10 | M8 | M8 | M16 | 48 |

### 7.2.2 Capacity Class 375 k



Unit: mm

| Type | Dimensions |  |  |  |  |  |  |  |  |  |  | Weight [kg] |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | X | Y | Z | Z1 | B | H | G | S | S1 | S2 | $\varnothing$ |  |
| FR-F 540L-375 k | 220 | 250 | 495 | 380 | 195 | 450 | 44 | M10 | M8 | M8 | M16 | 57 |

### 7.2.3 Capacity Classes 450 k and 530 k



Weight: 100kg


Unit: mm

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